

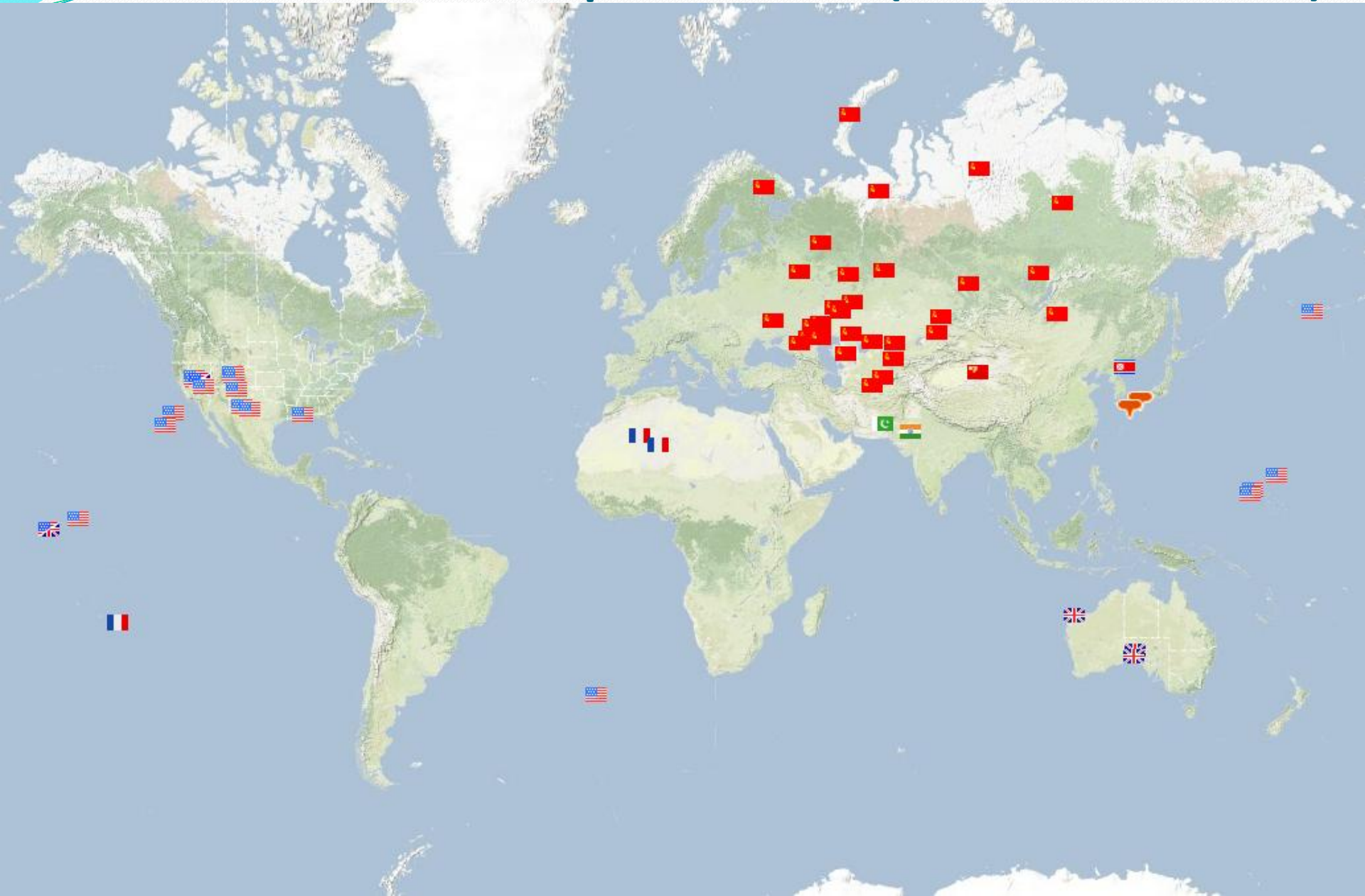
# Global seismic monitoring: A Bayesian approach

Nimar Arora

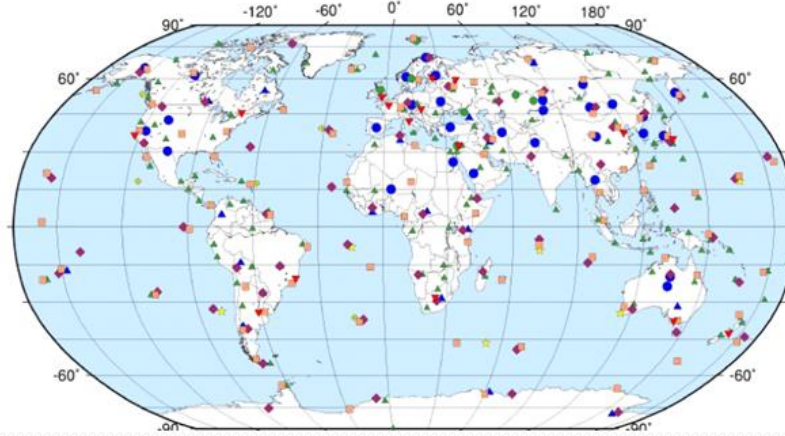
*Computer Science, UC Berkeley*

Joint work with Stuart Russell, Erik Sudderth, and Paul Kidwell

# 2053 Nuclear Explosions (1945 - 2009)



# CTBT & IMS



seismic stations  
other stations

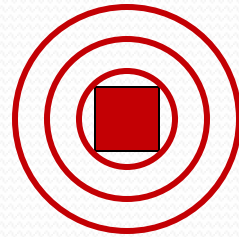
- Bans all testing of nuclear weapons on earth
  - Allows for outside inspection of 1000km<sup>2</sup>
- ~ 110 seismic stations in IMS (International Monitoring System)
- Need 9 more ratifications including US, China
- US Senate refused to ratify in 1998
  - “too hard to monitor”

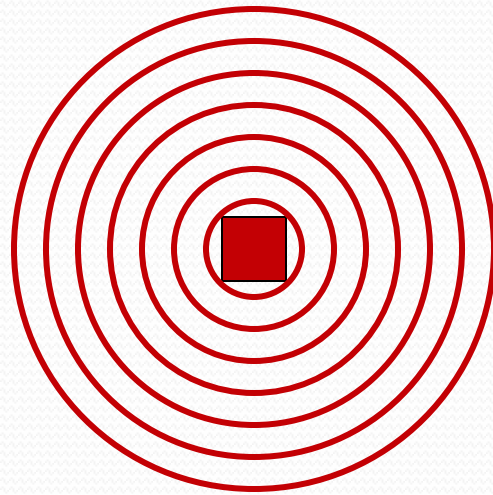
# Overview

- **Seismology**
- Generative Model
- Inference
- Results

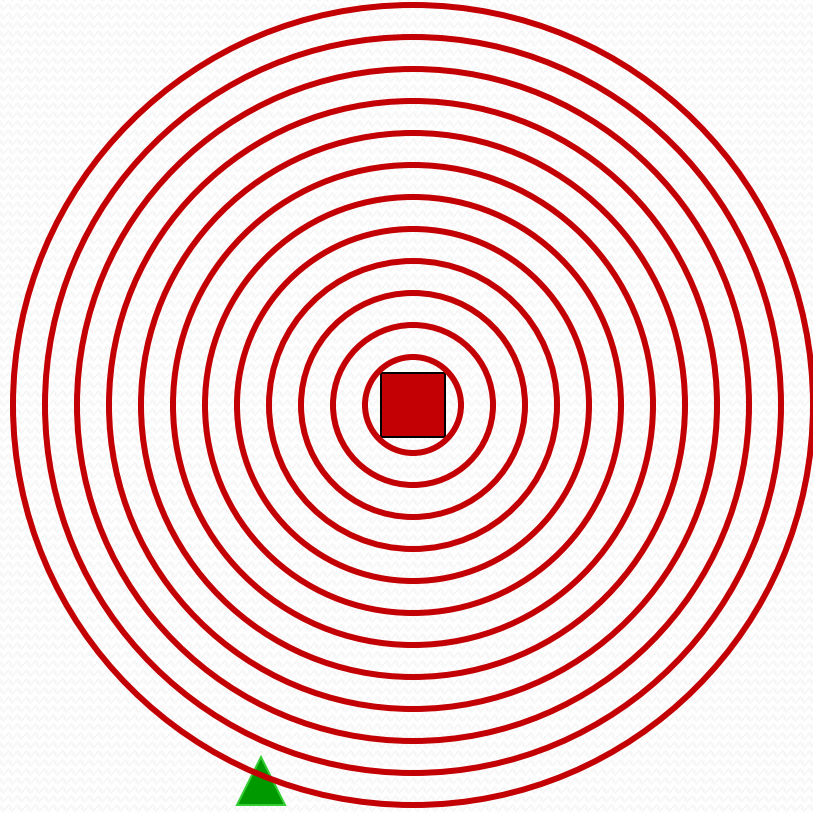






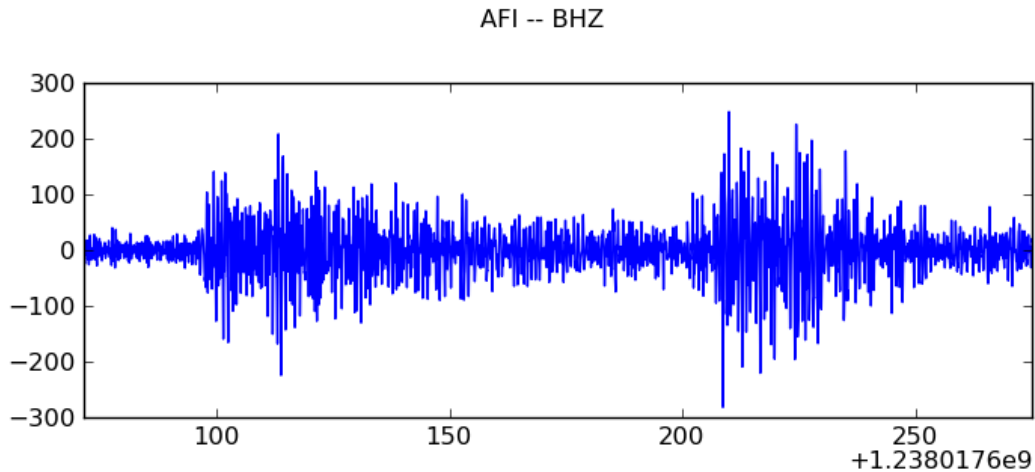




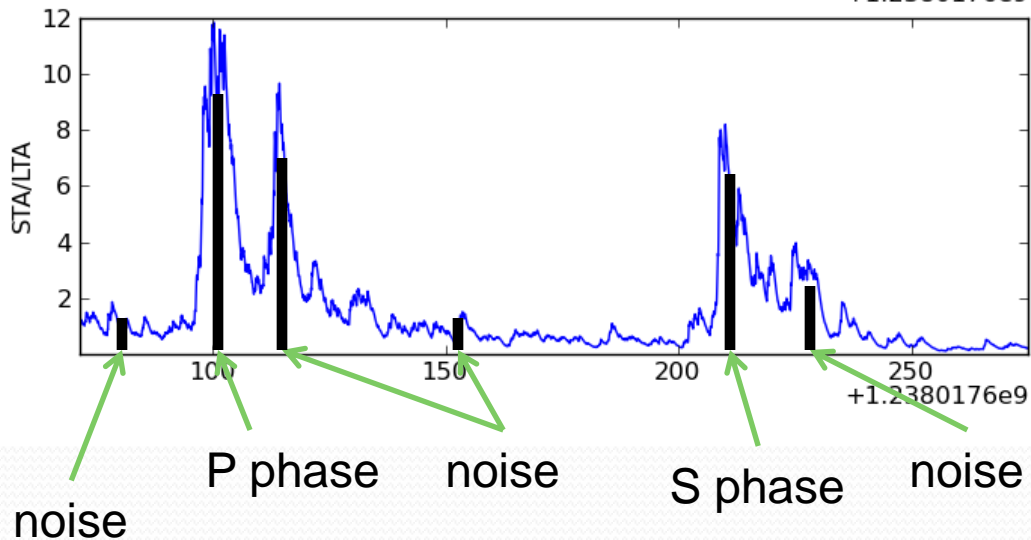


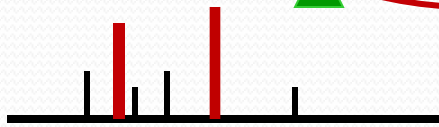
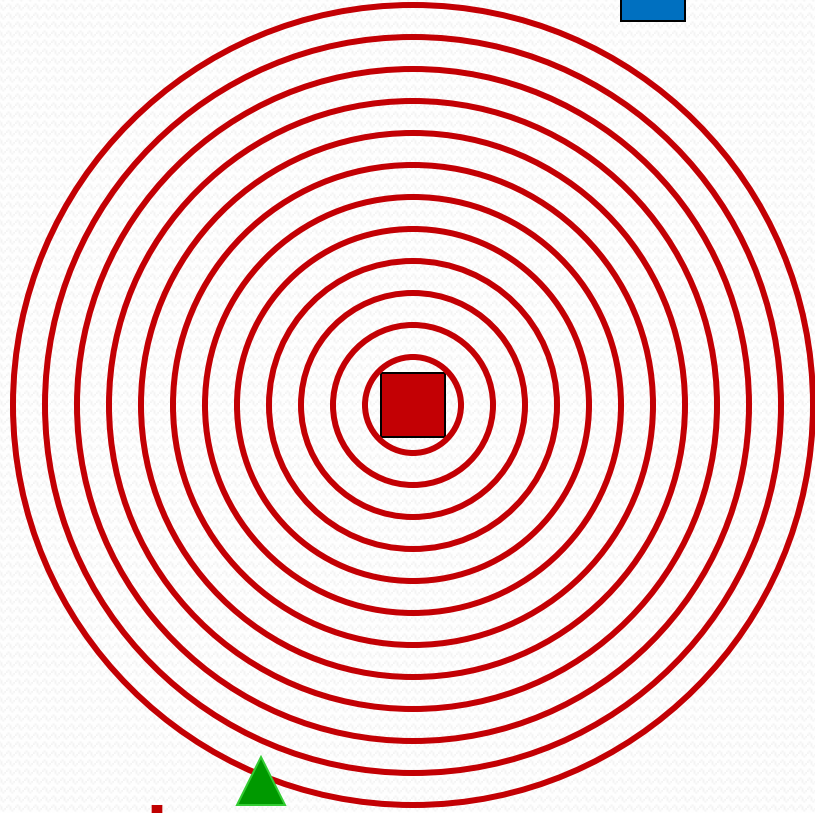
# Waveforms → Detections

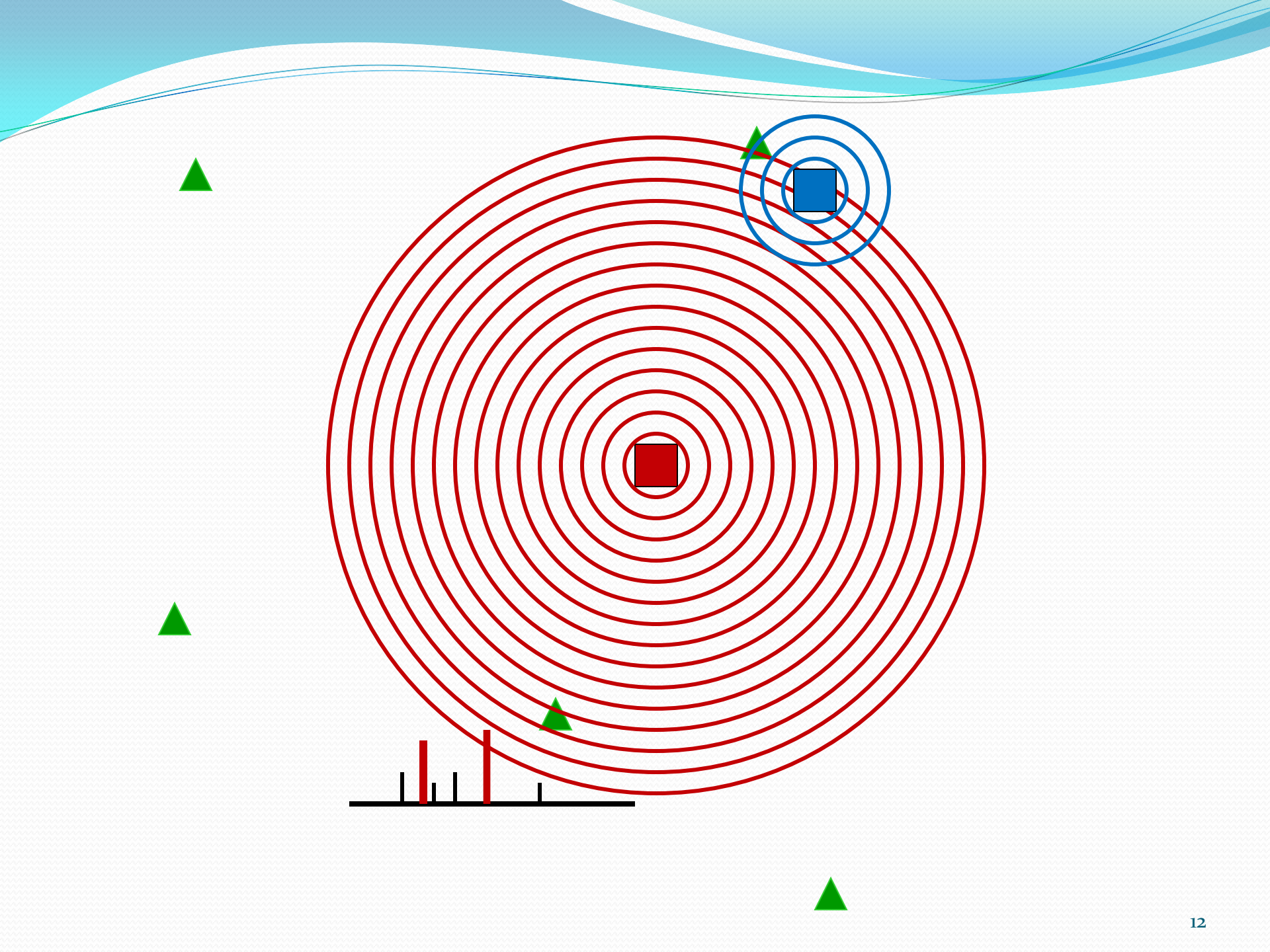
Filtered Waveform  
(1-4 Hz)

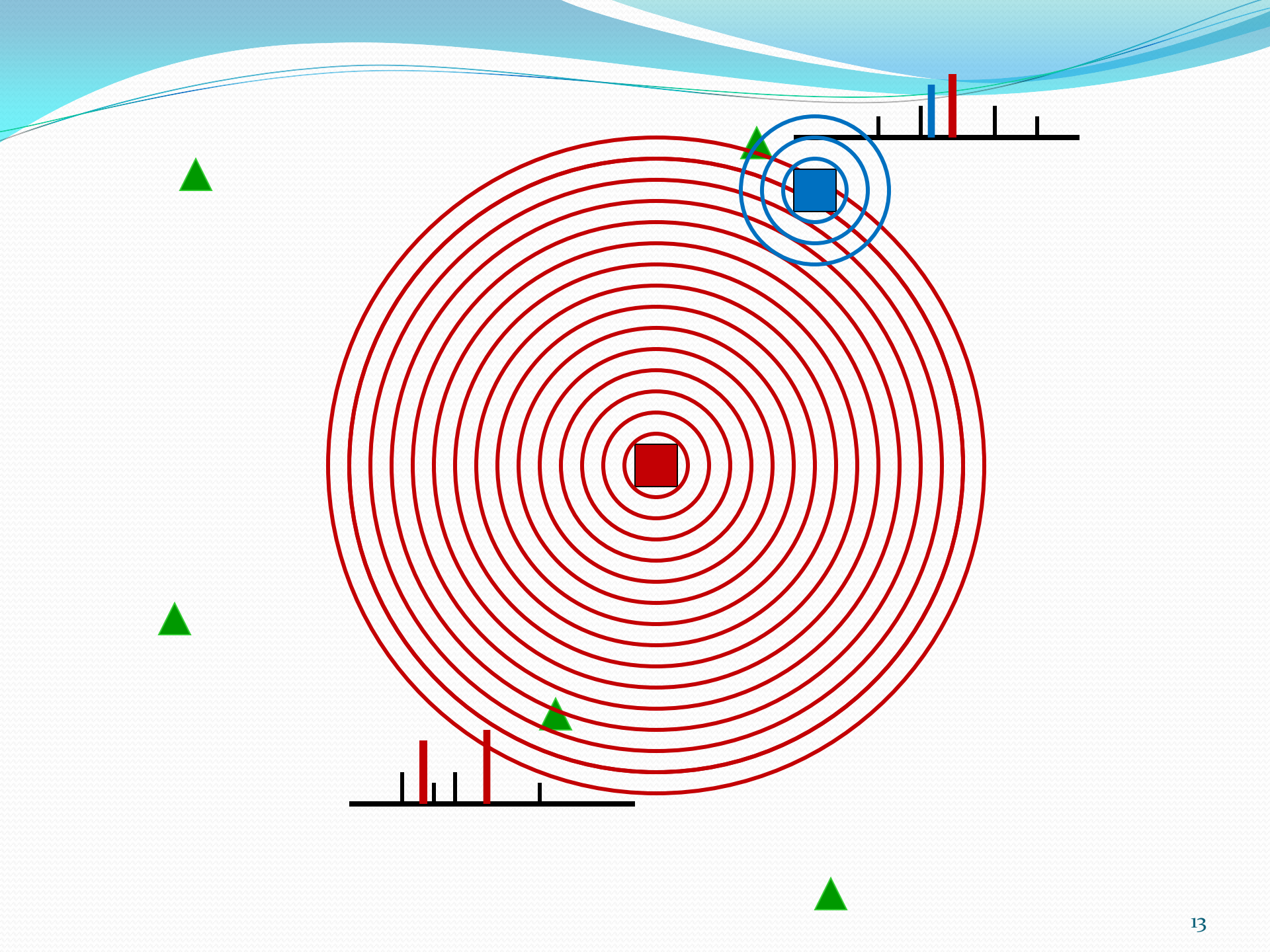


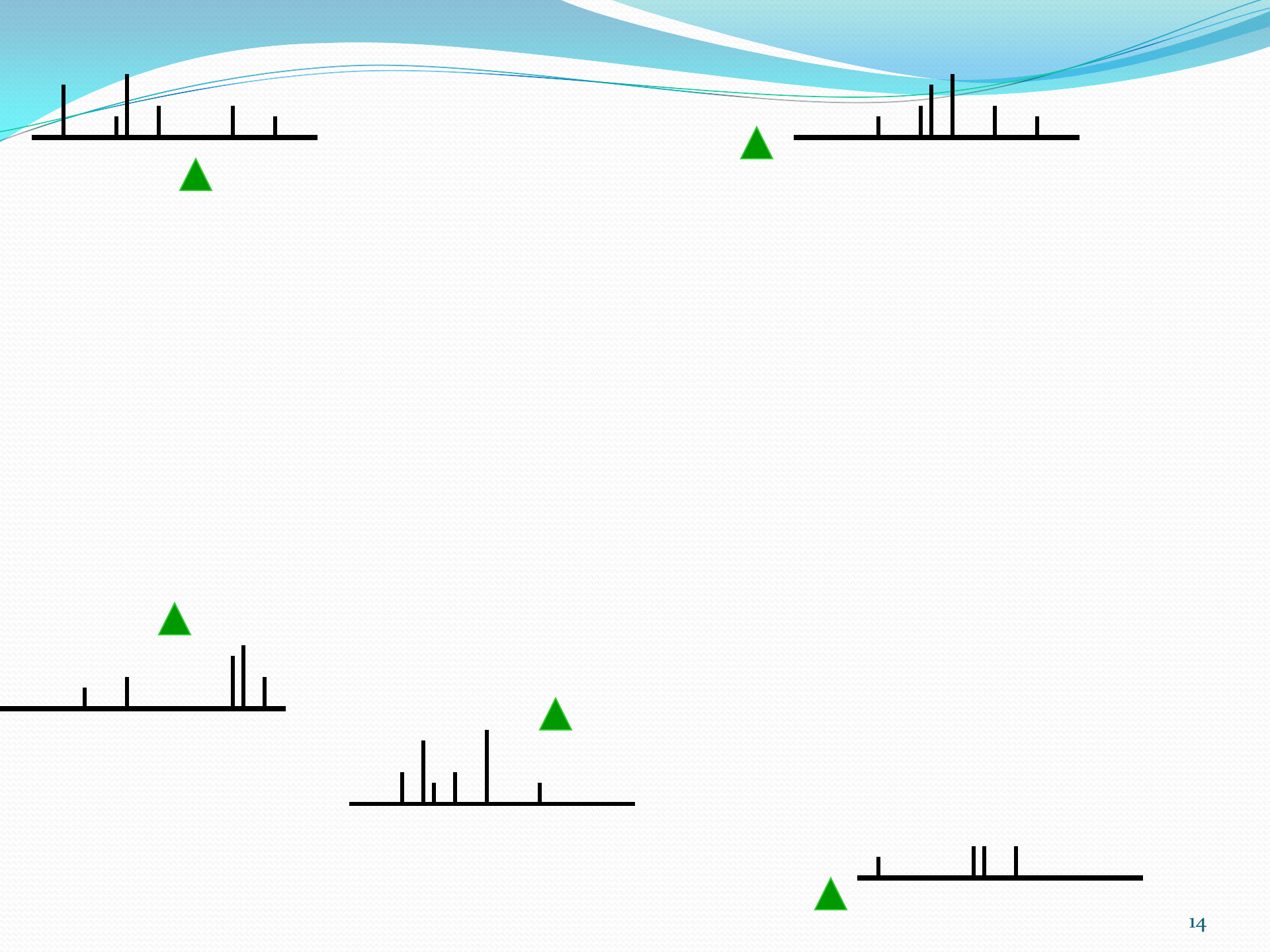
Short-term (1.5s)  
divided by  
long-term (60s)  
average











# Why is the problem hard?

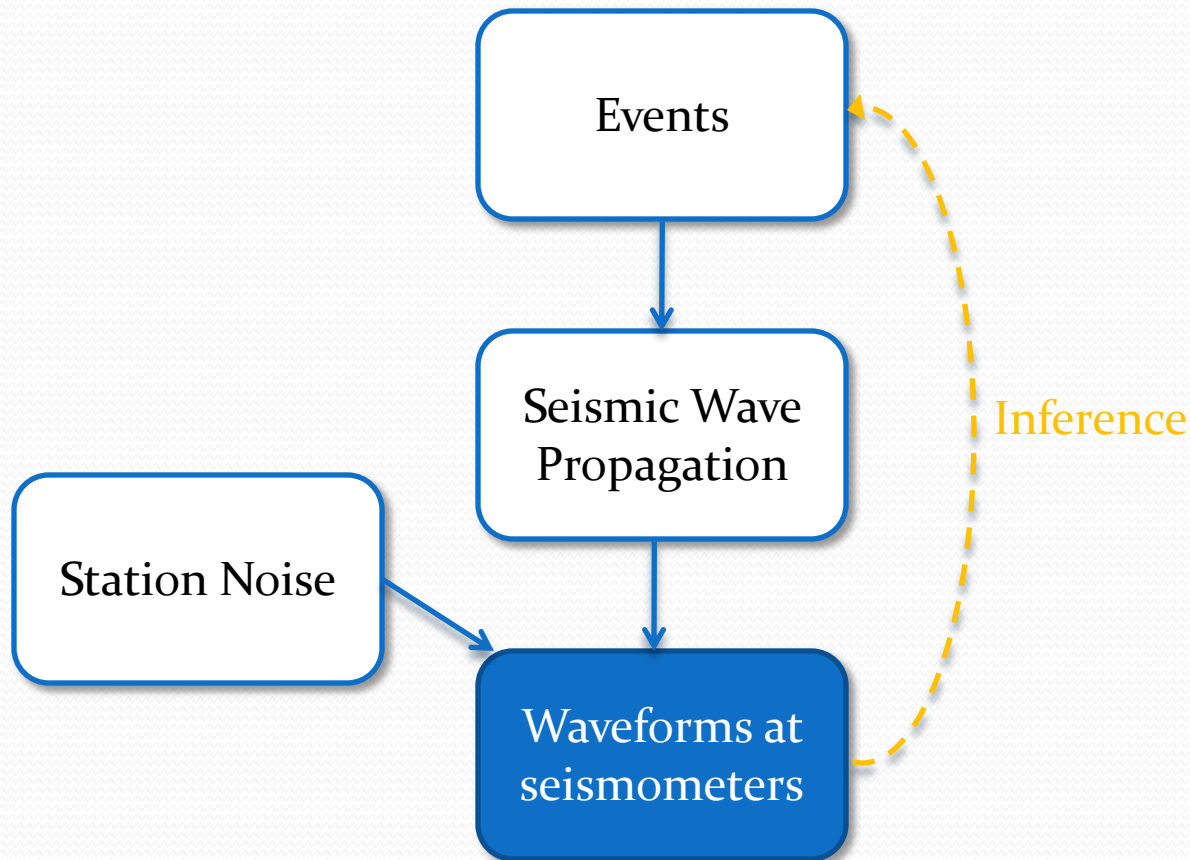
- ~10000 “detections” per day, 90% from noise (less than magnitude 2 events)
- CTBT needs to find *all* seismic events
- CTBT automated system (**SEL<sub>3</sub>**) finds 69% of significant events and half the predicted events are spurious (nonexistent)
- 16 human analysts are required to fix these errors, and generate **LEB** (“ground truth”)
- Unreliable below magnitude 4 (1kT)

# Overview

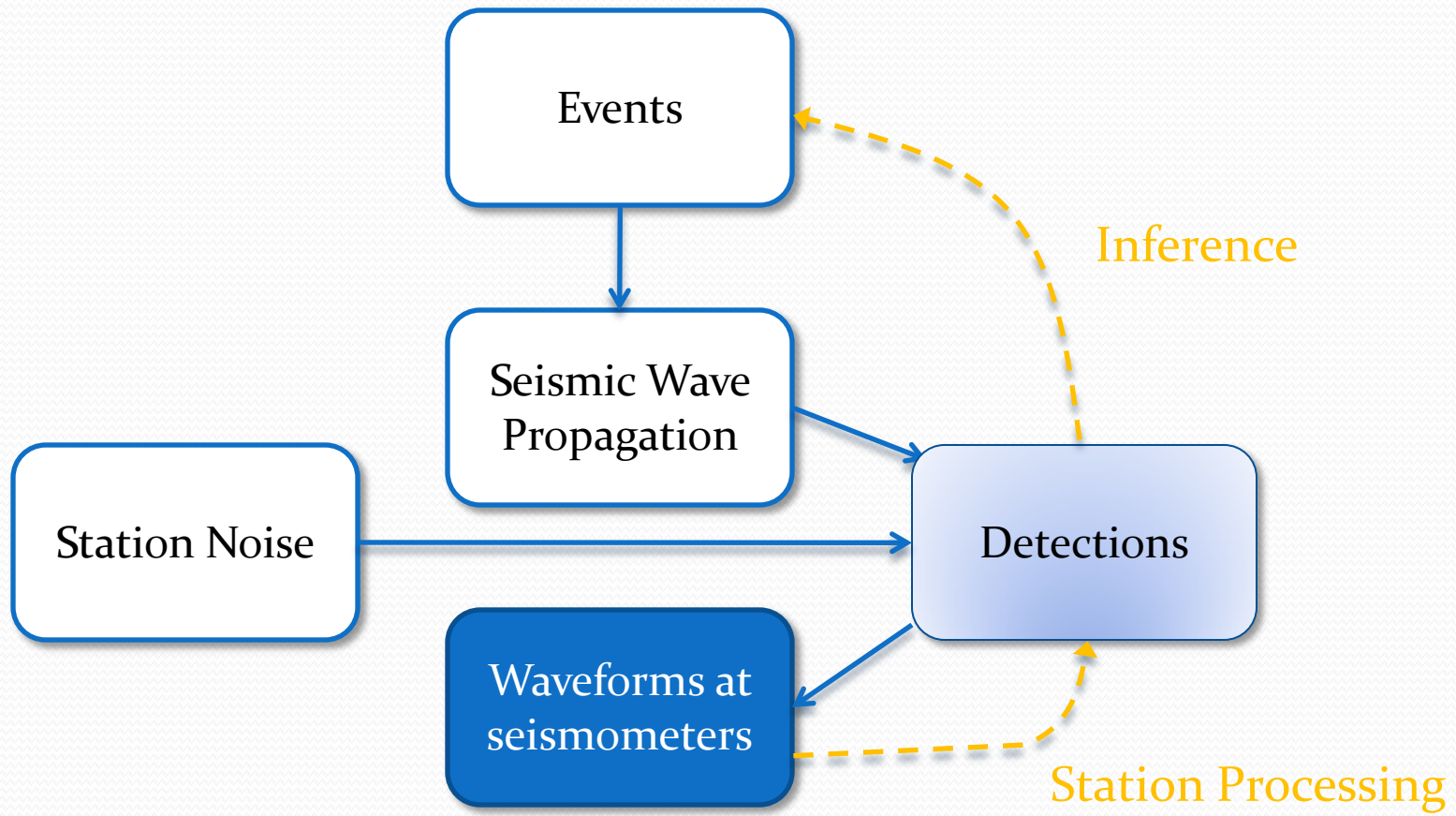
- Seismology
- **Generative Model**
- Inference
- Results



# Vertically Integrated Seismic Analysis (VISA)



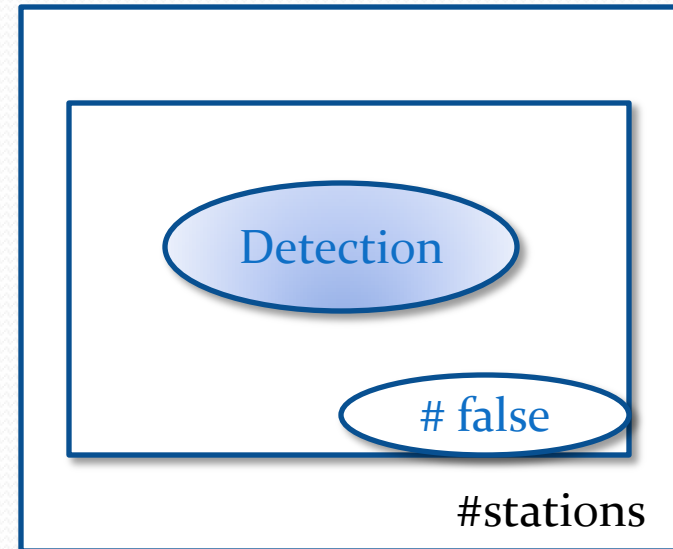
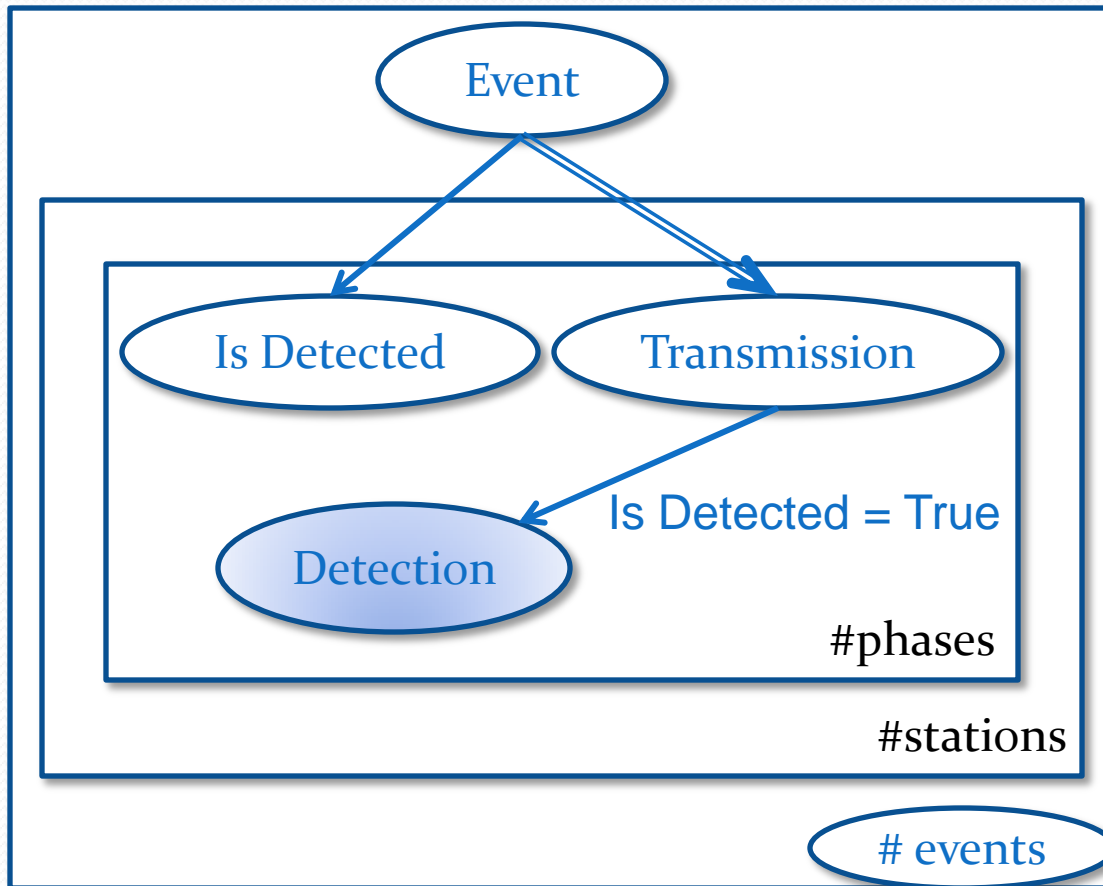
# Network Processing (NET-VISA)



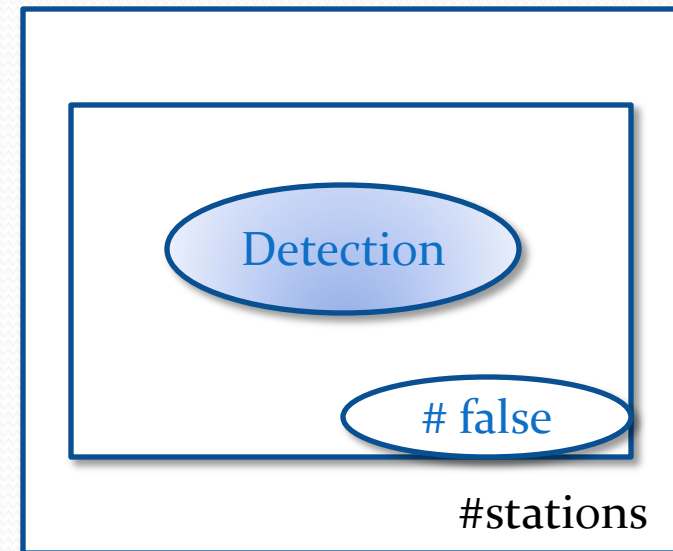
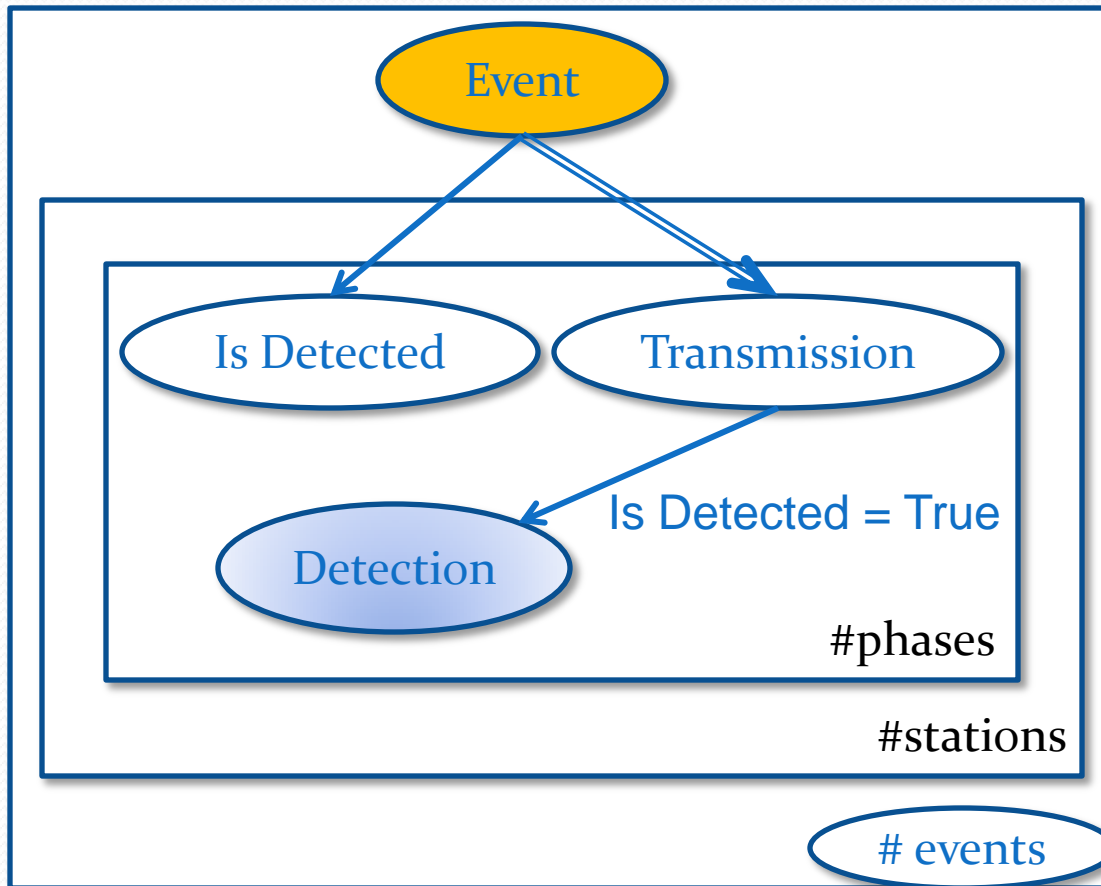
# Expressed in BLOG (Bayesian Logic)

```
# SeismicEvents ~ Poisson[TIME_DURATION*EVENT_RATE];
IsEarthQuake(e) ~ Bernoulli(.999);
EventLocation(e) ~ If IsEarthQuake(e) then EarthQuakeDistribution()
                    Else UniformEarthDistribution();
Magnitude(e) ~ Exponential(log(10)) + MIN_MAG;
Distance(e,s) = GeographicalDistance(EventLocation(e), SiteLocation(s));
IsDetected(e,p,s) ~ Logistic[SITE_COEFFS(s,p)](Magnitude(e), Distance(e,s));
# Arrivals(site = s) ~ Poisson[TIME_DURATION*FALSE_RATE(s)];
# Arrivals(event=e, site=s) = If IsDetected(e,s) then 1 else 0;
Time(a) ~ If (event(a) = null) then Uniform(0,TIME_DURATION)
            else IASPEI(EventLocation(event(a)),SiteLocation(site(a)),Phase(a)) + TimeRes(a);
TimeRes(a) ~ Laplace(TIMLOC(site(a)), TIMSCALE(site(a)));
Azimuth(a) ~ If (event(a) = null) then Uniform(0, 360)
              else = GeoAzimuth(EventLocation(event(a)),SiteLocation(site(a)) + AzRes(a);
AzRes(a) ~ Laplace(AZLOC(site(a)) AZSCALE(site(a)));
Slow(a) ~ If (event(a) = null) then Uniform(0,20)
            else = IASPEI-SLOW(EventLocation(event(a)),SiteLocation(site(a)) + SlowRes(site(a));
SloRes(a) ~ Laplace(SLOLOC(site(a)), SLOSCALE(site(a)));
```

# Generative Model

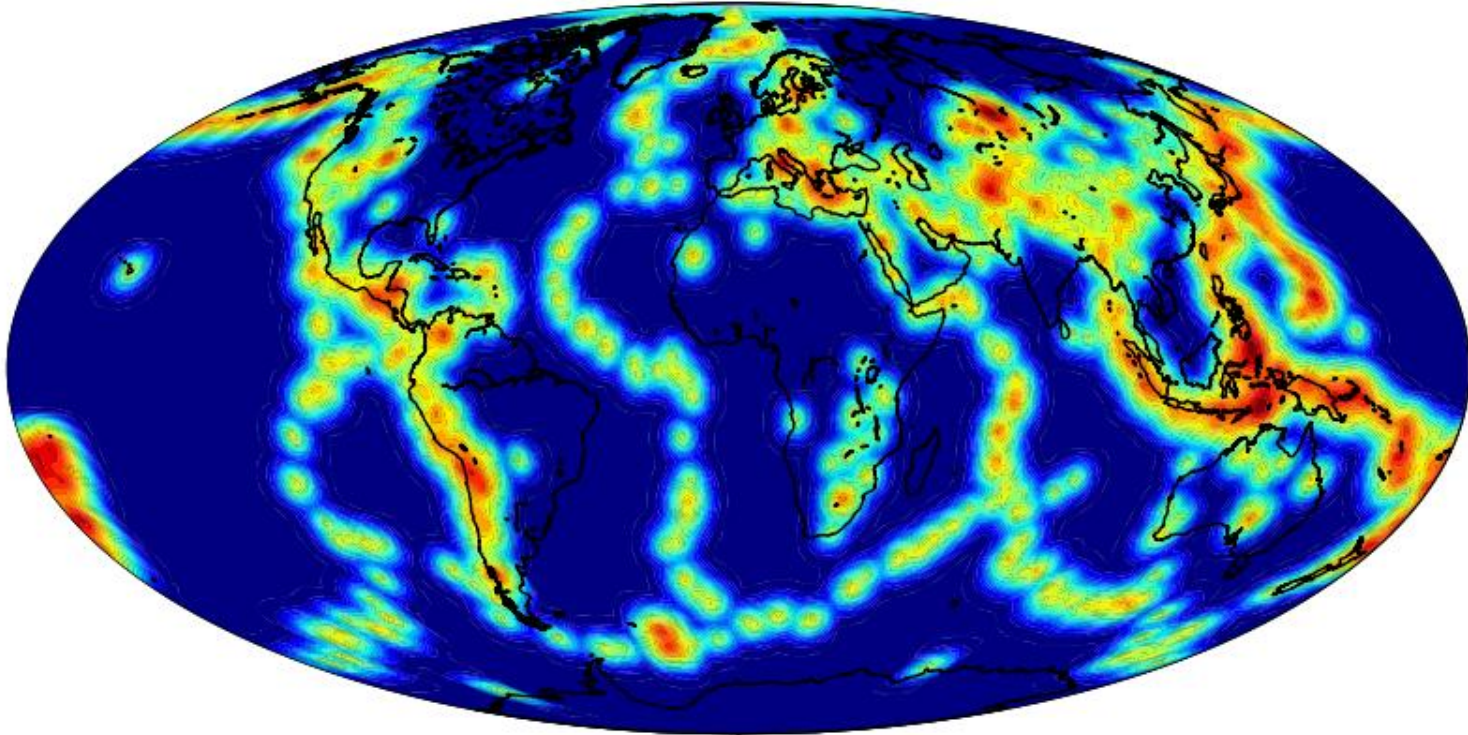


# Generative Model

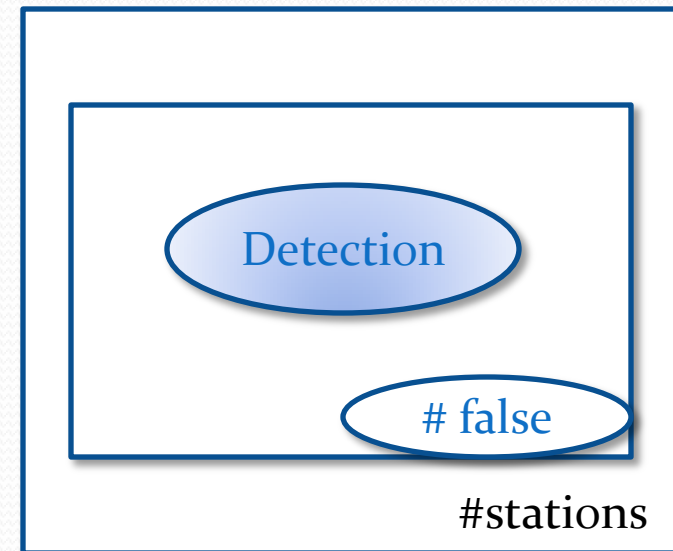
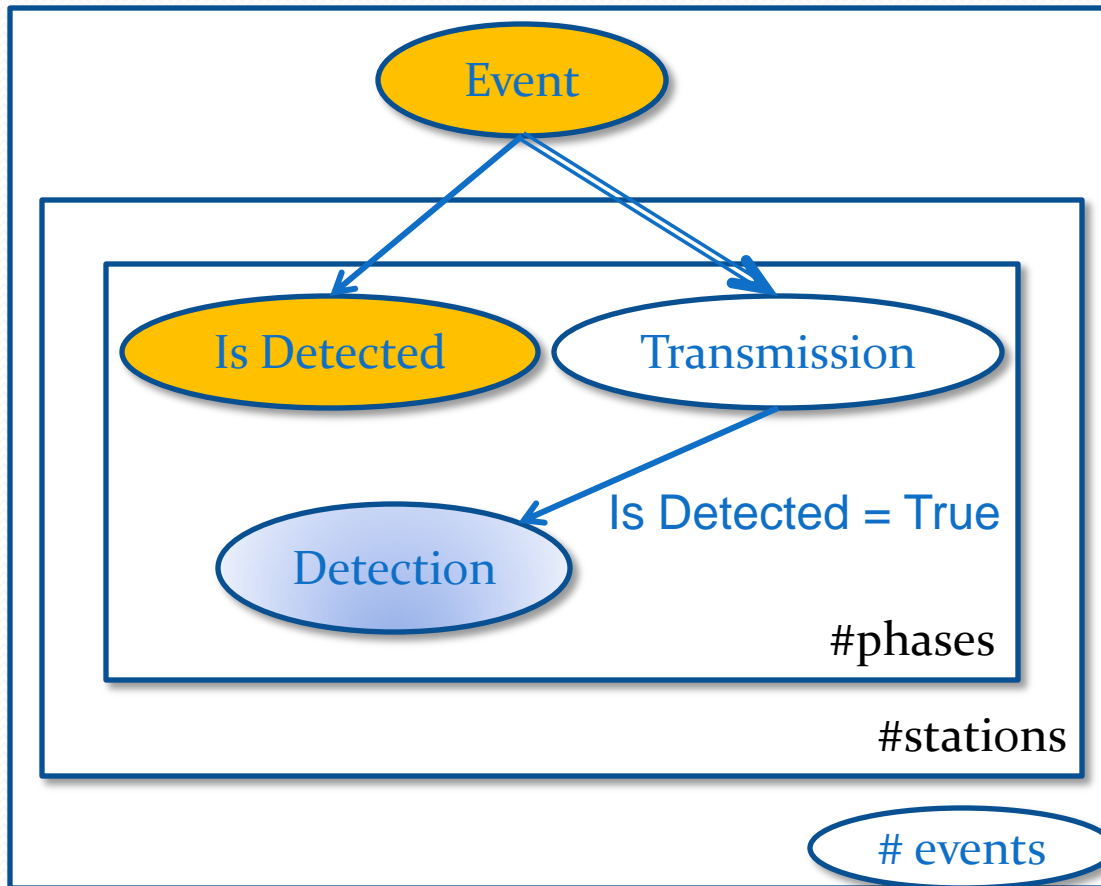


# Generative Model – Event Location

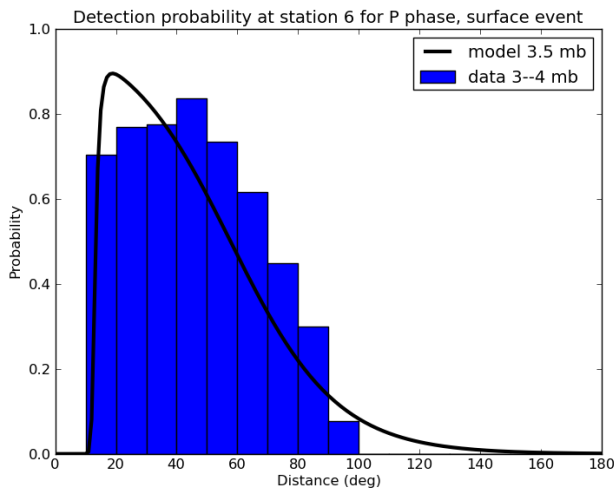
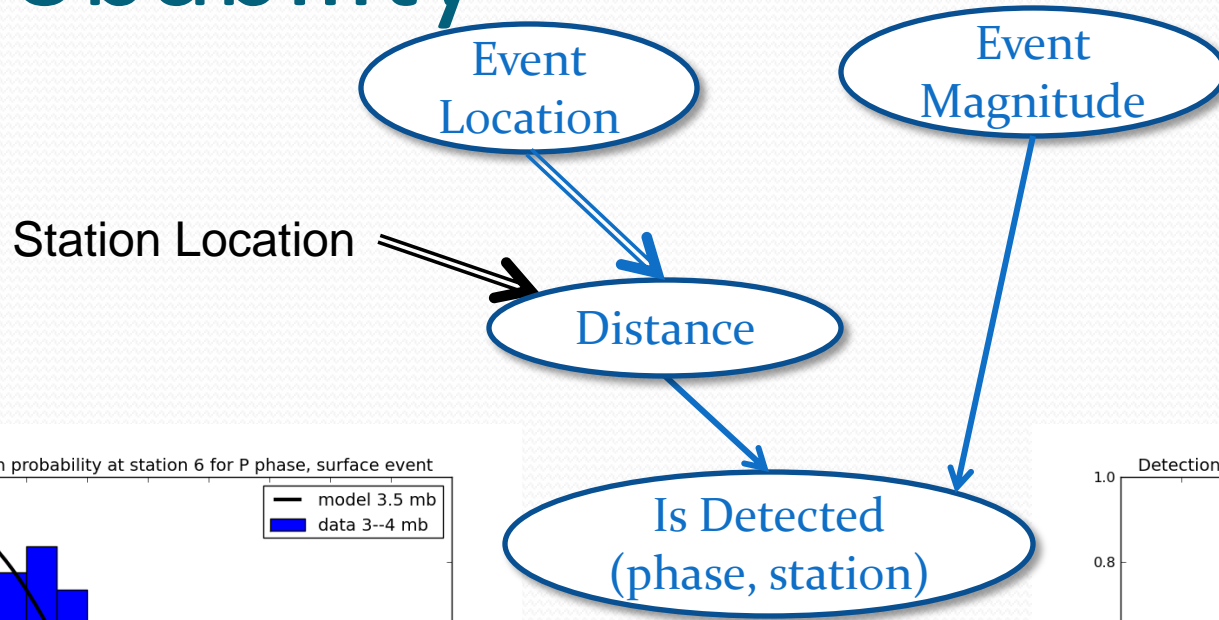
Log Prior Density of Events



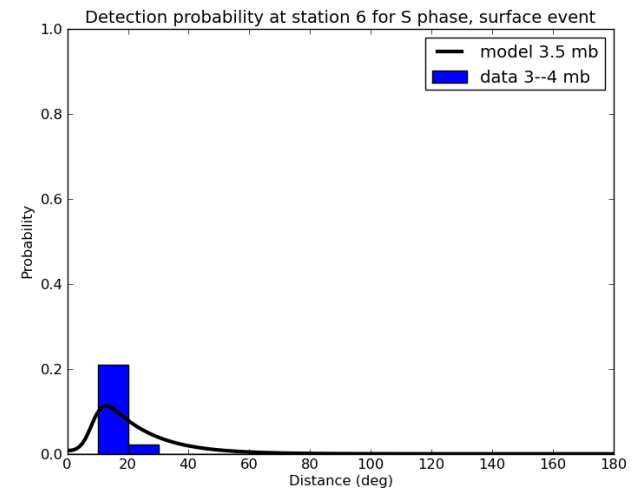
# Generative Model



# Generative Model – Detection Probability



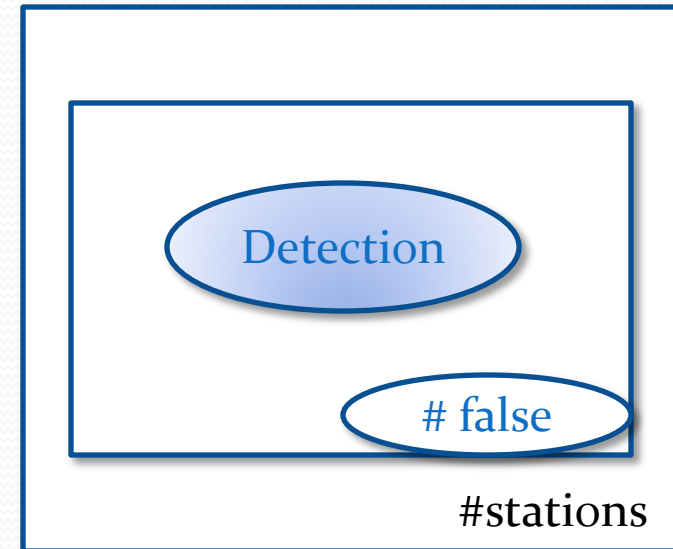
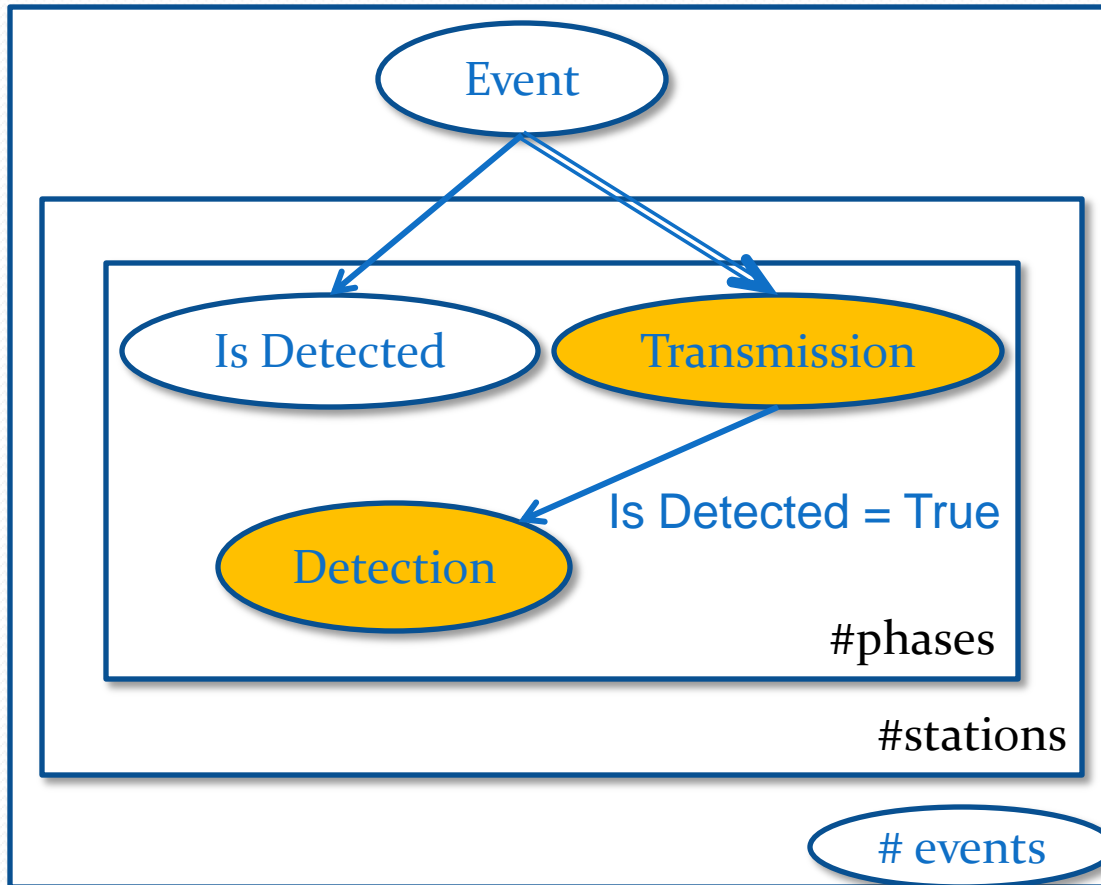
P phase, station 6



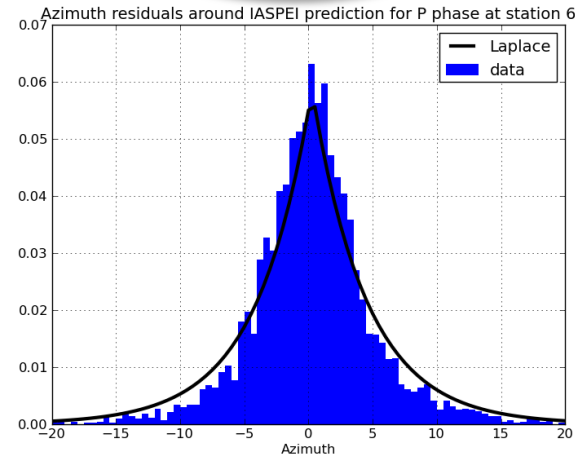
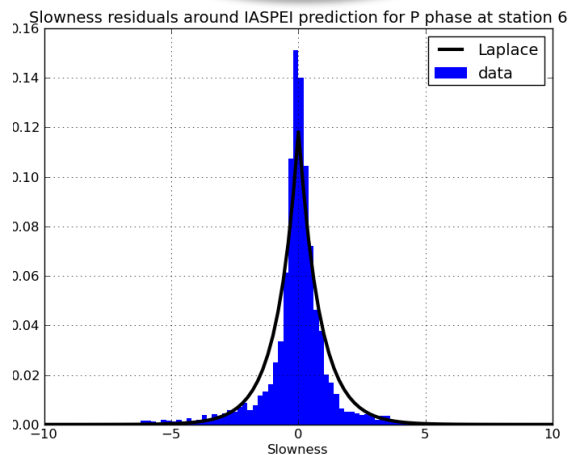
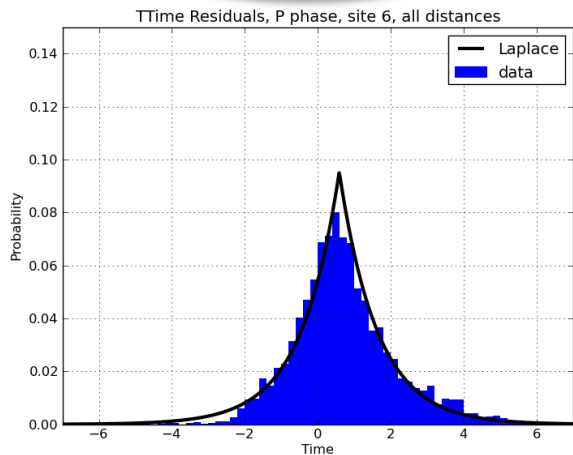
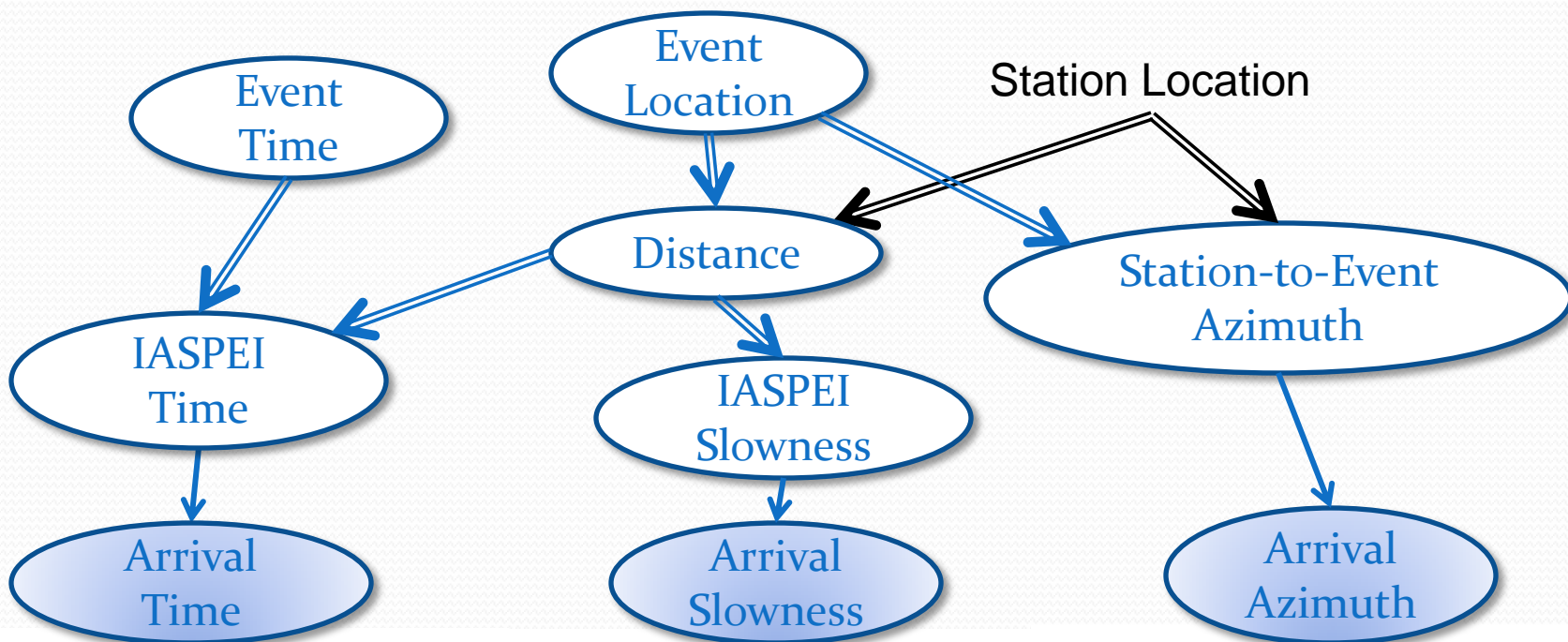
S phase, station 6



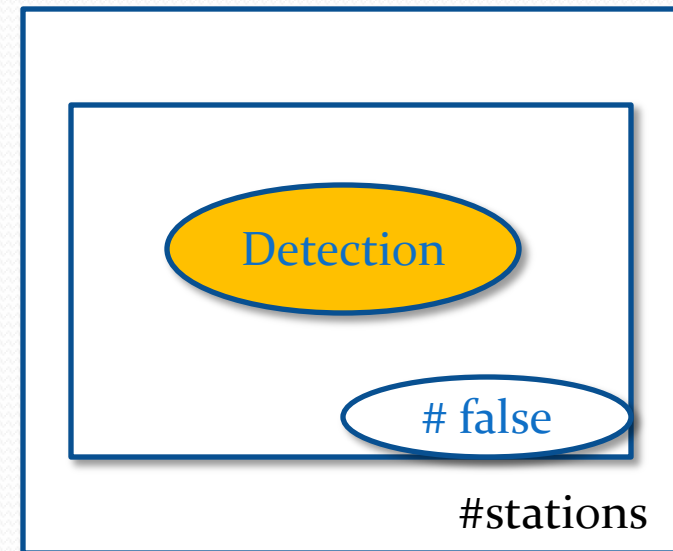
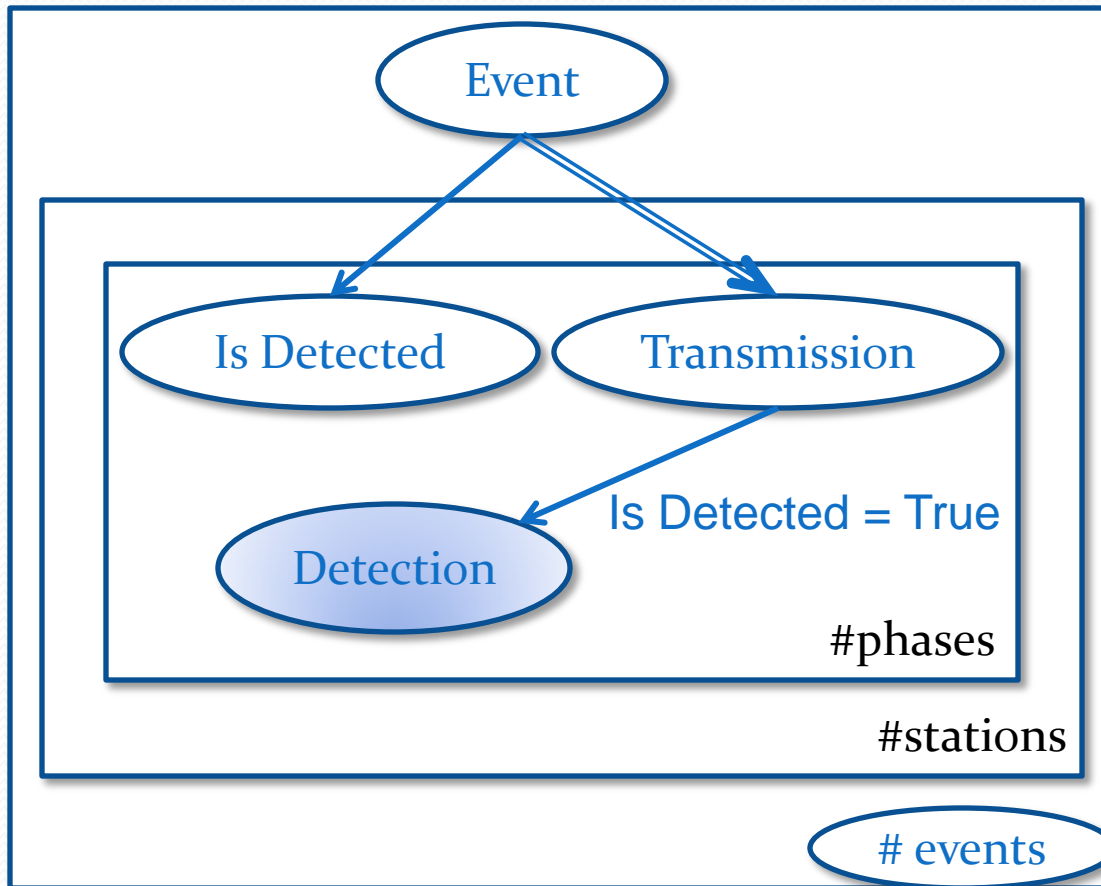
# Generative Model



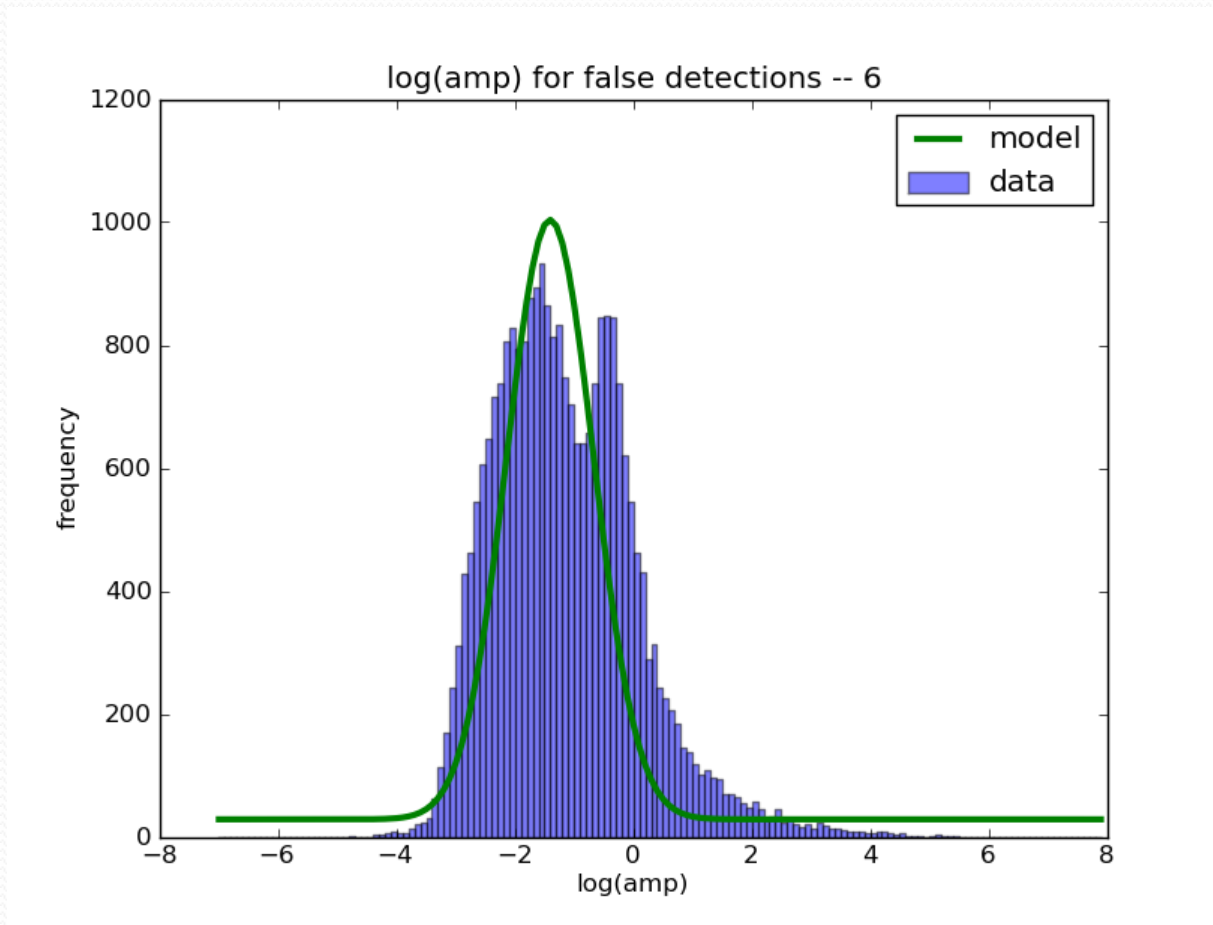
# Generative Model – Arrival Time, Azimuth, Slowness



# Generative Model



# Noise Amplitude & Rate



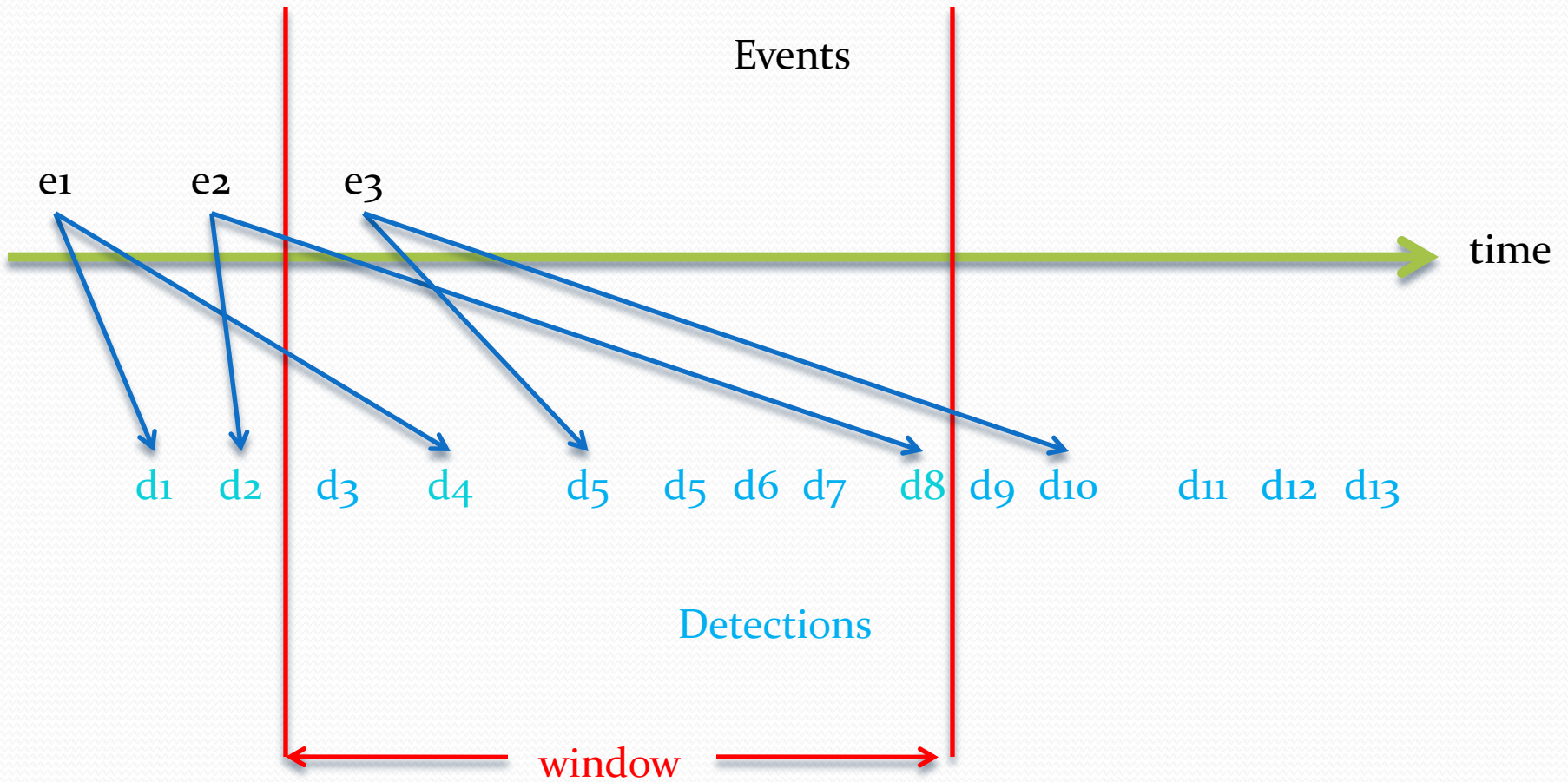
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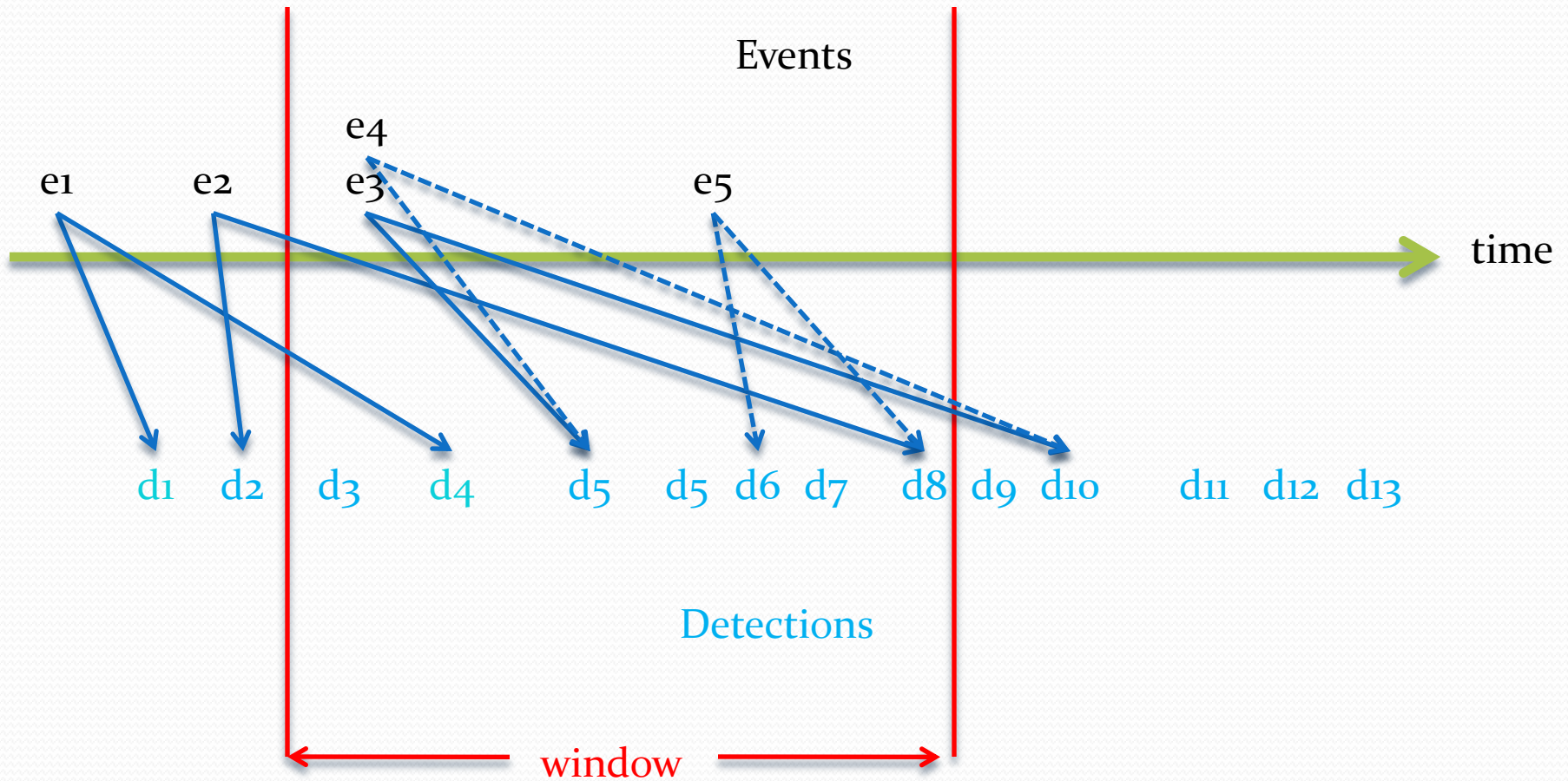
# Inference Overview

- *Max a-posteriori* (MAP) seismic event bulletin
- Easier to compare to SEL<sub>3</sub>
- Continuously incorporate new detections in the hypothesis
- Heuristic search moves improve the probability
  - Birth
  - Reassociate
  - Relocate
  - Death

# Inference Example

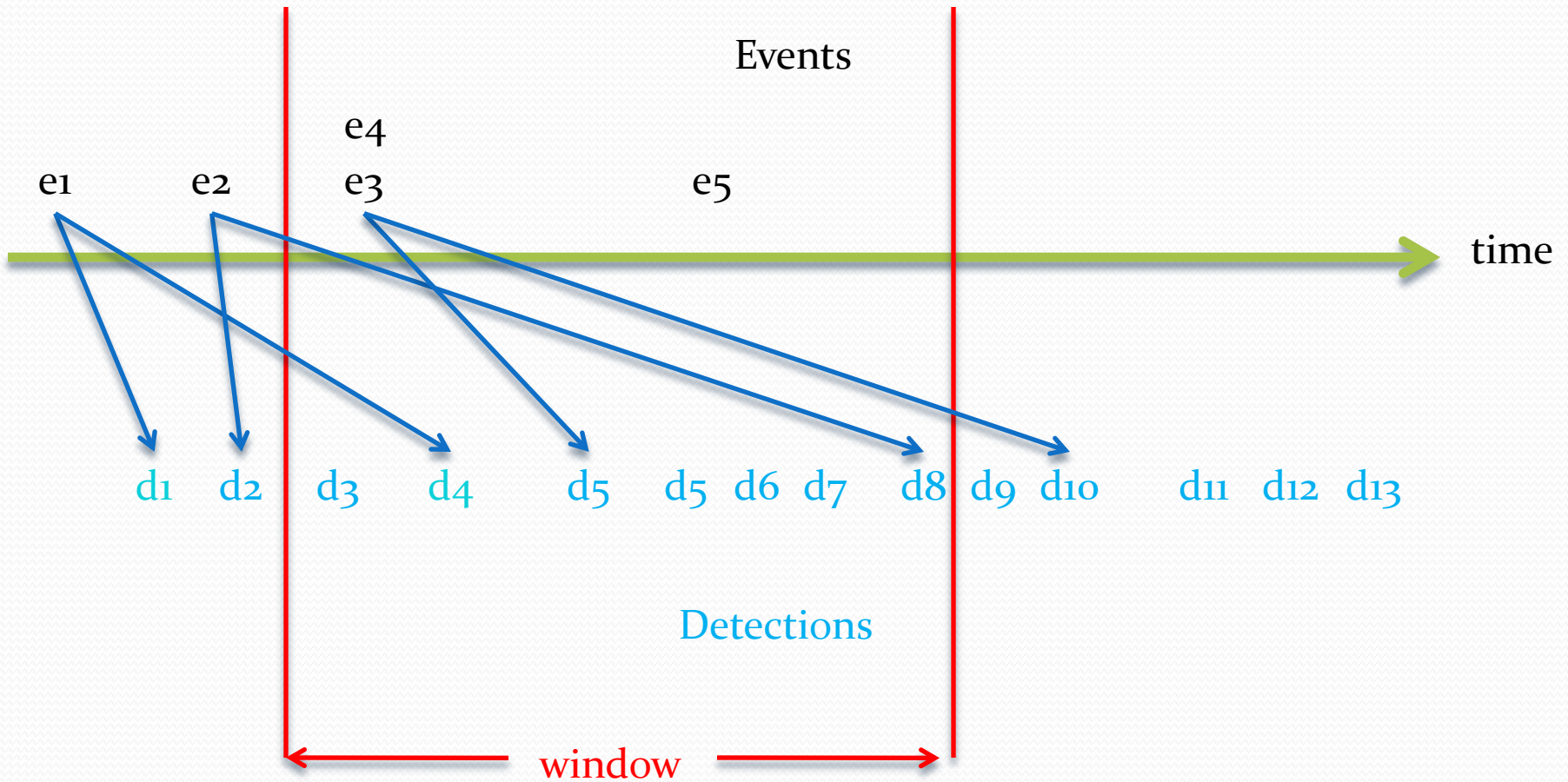


# Inference : Birth Move

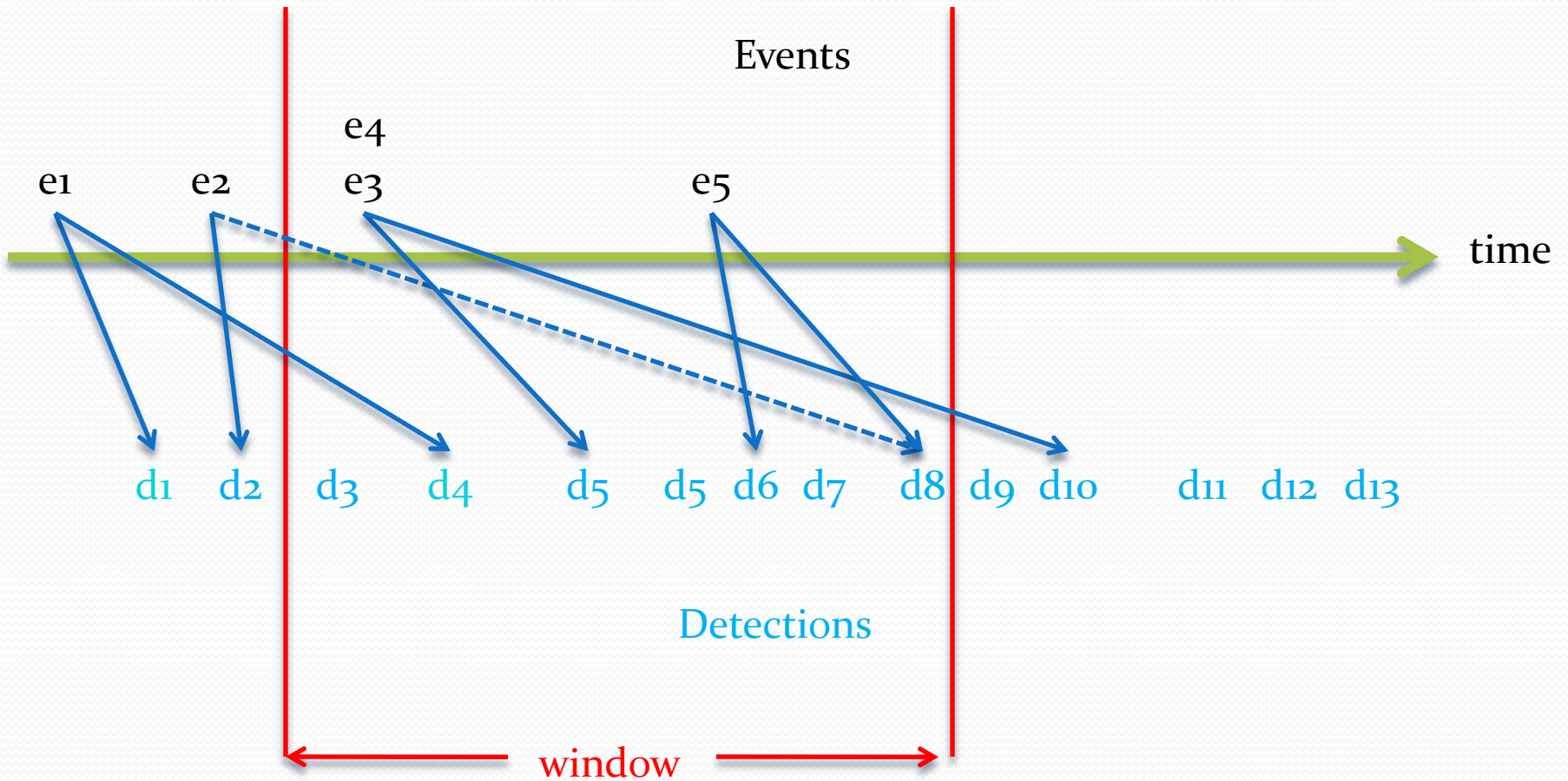




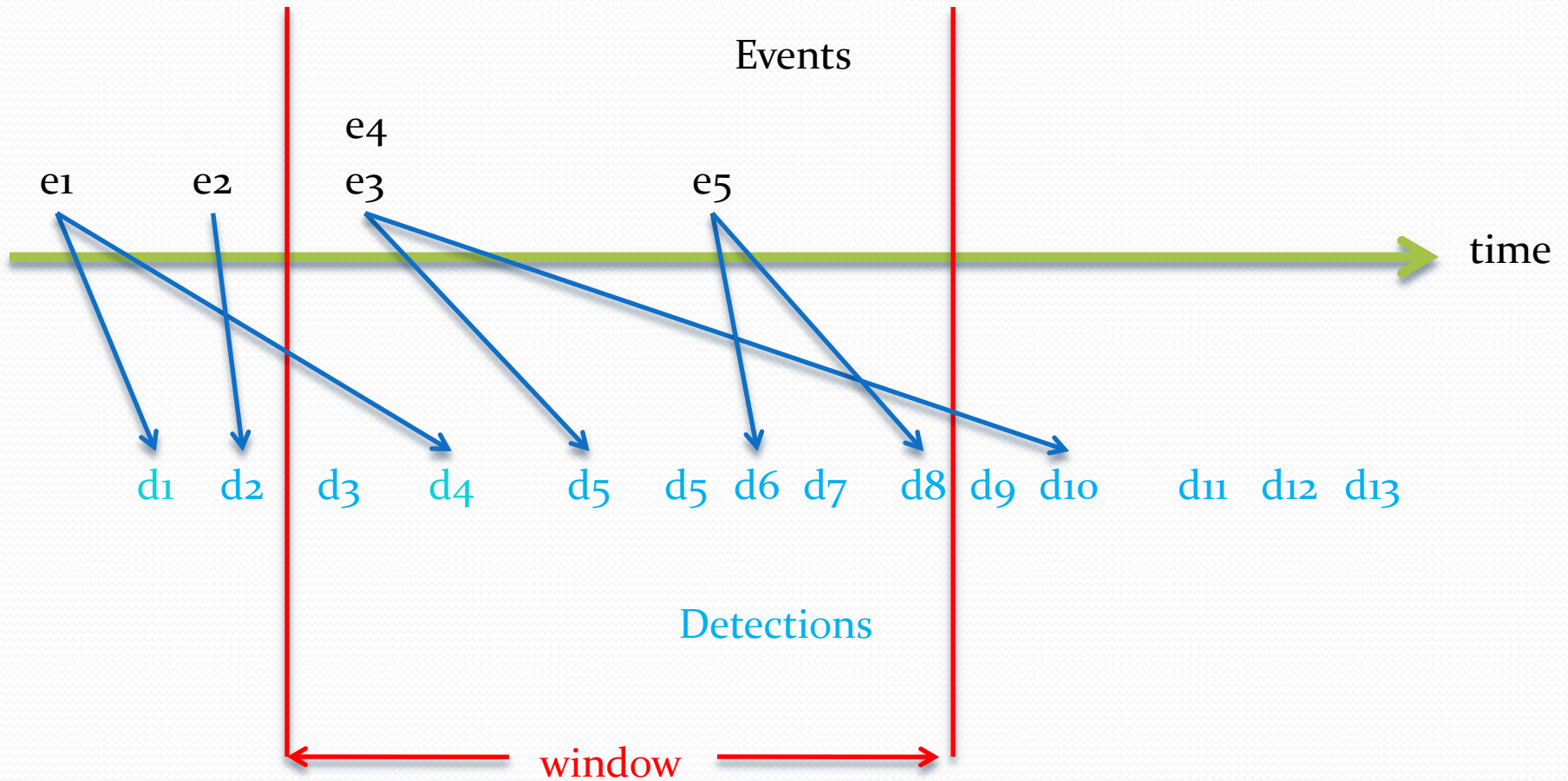
# Inference : Birth Move



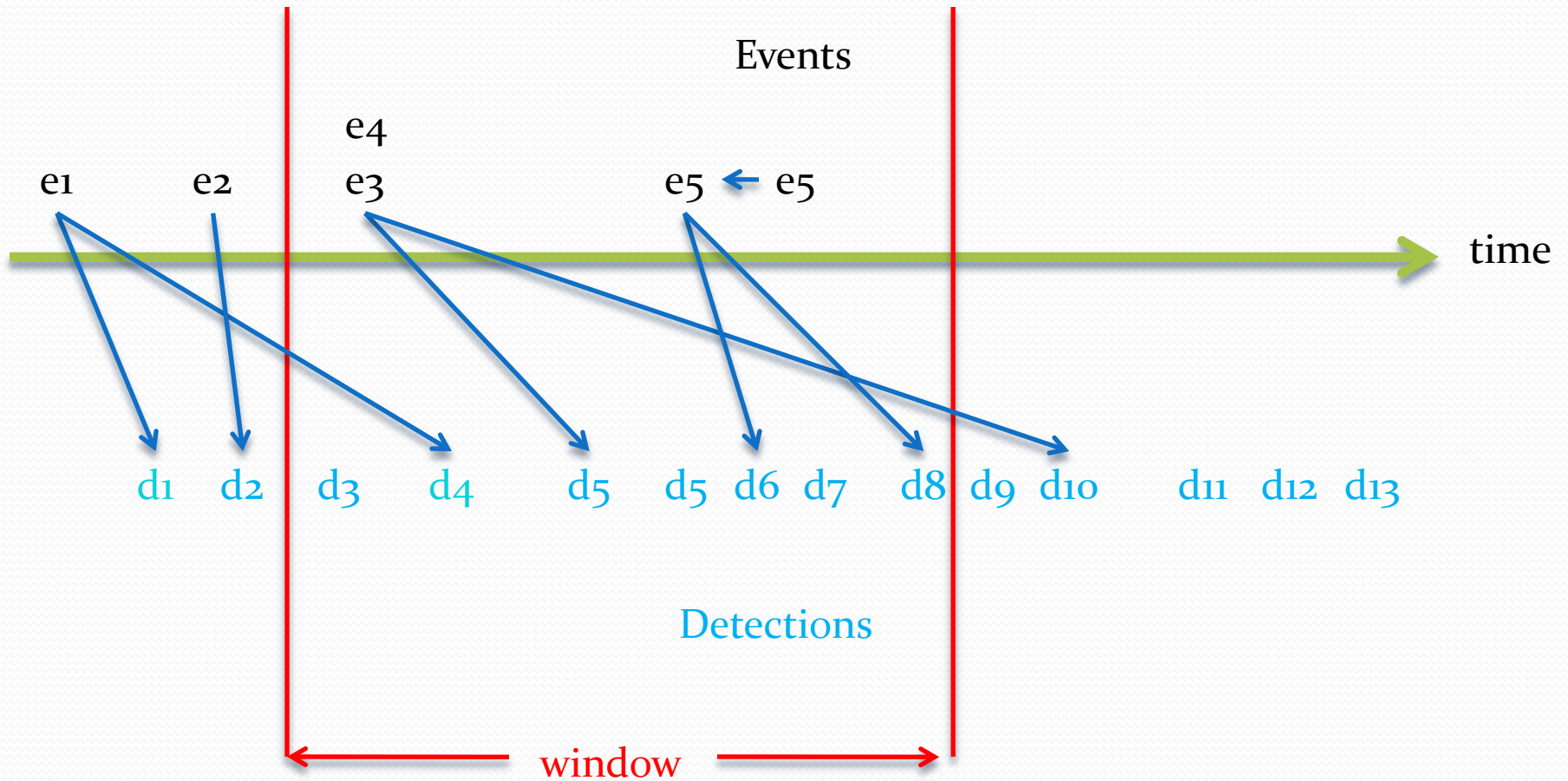
# Inference : Reassociate Detections



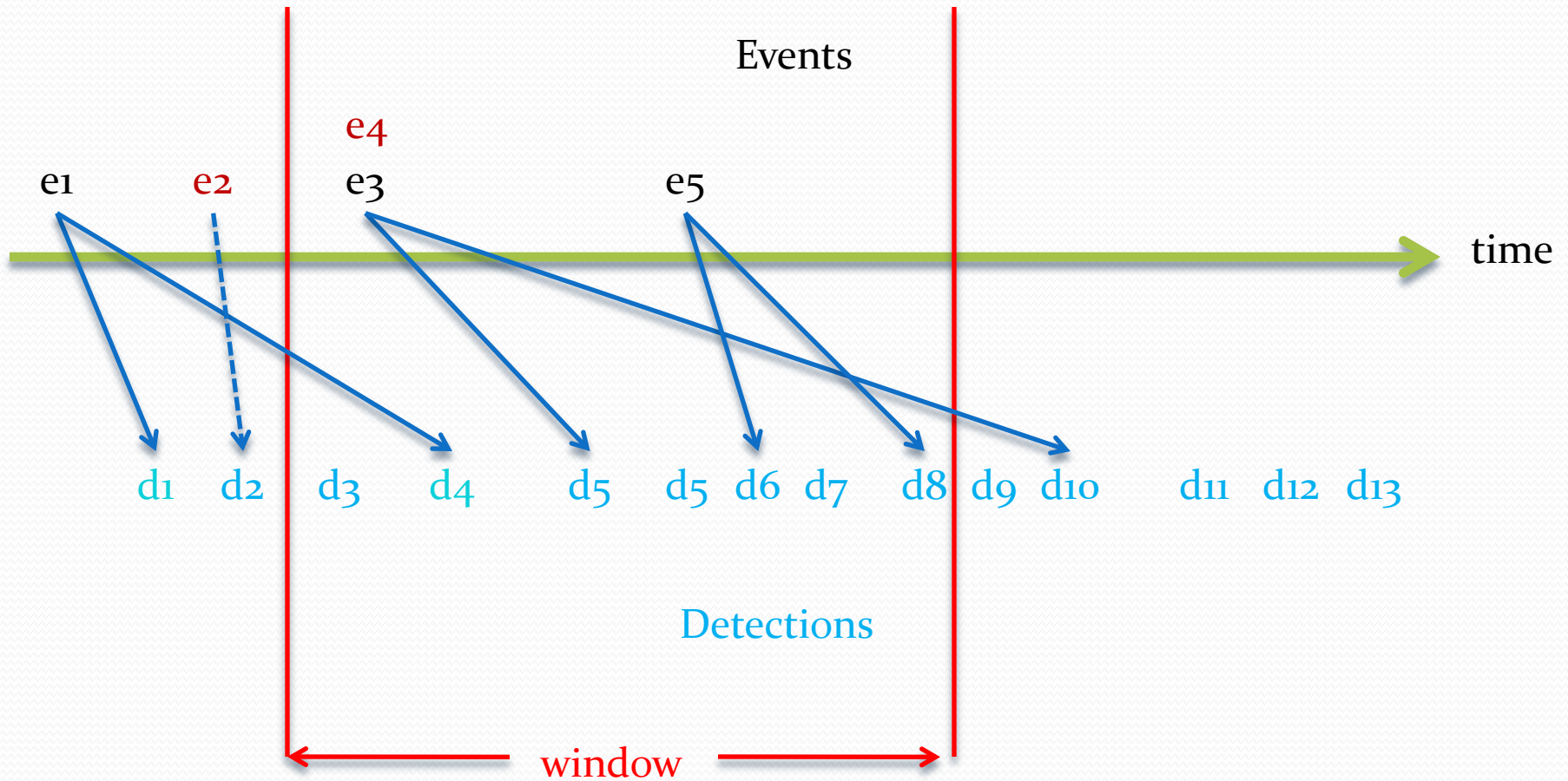
# Inference : Reassociate Detections



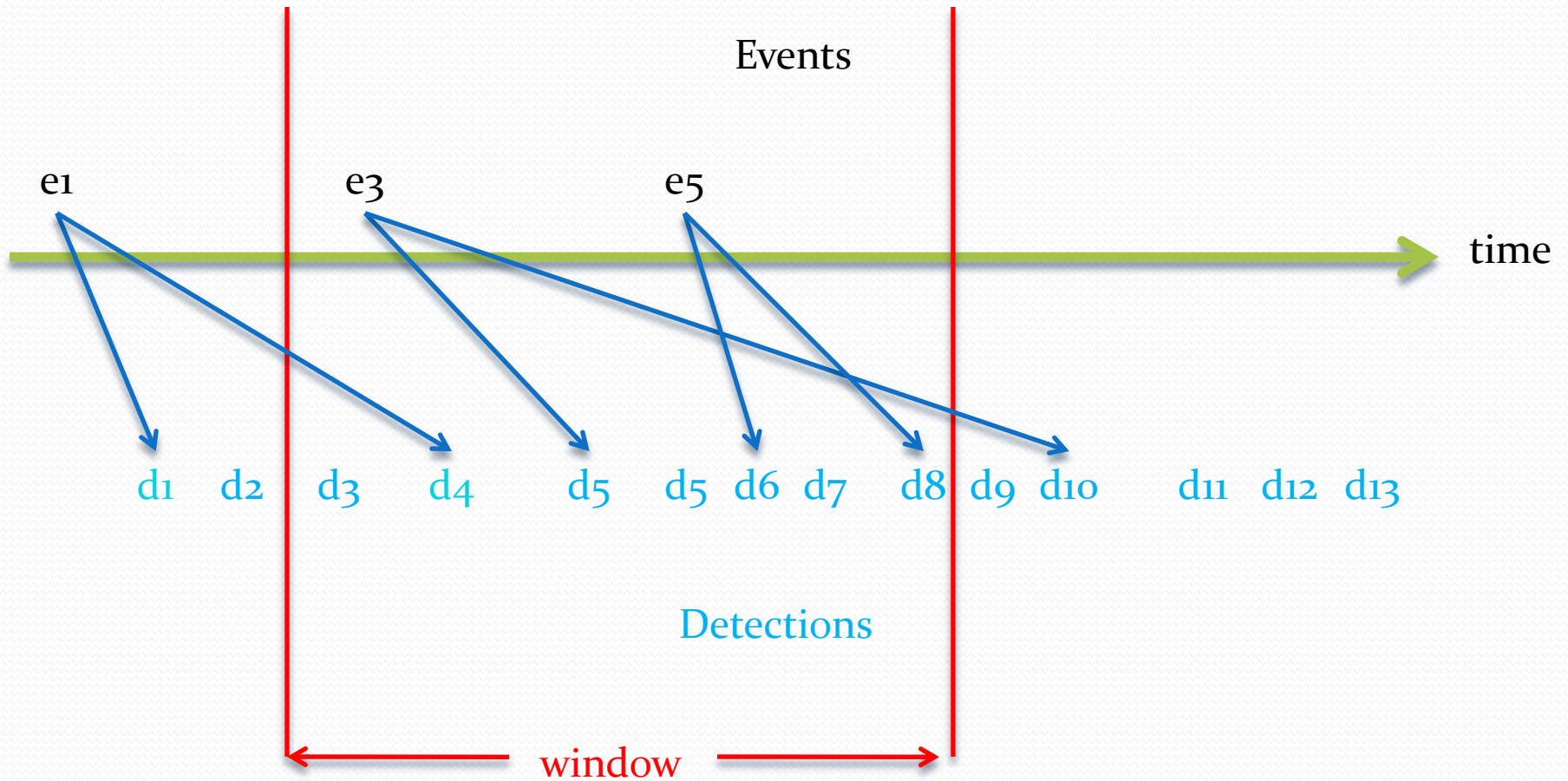
# Inference : Relocate Events



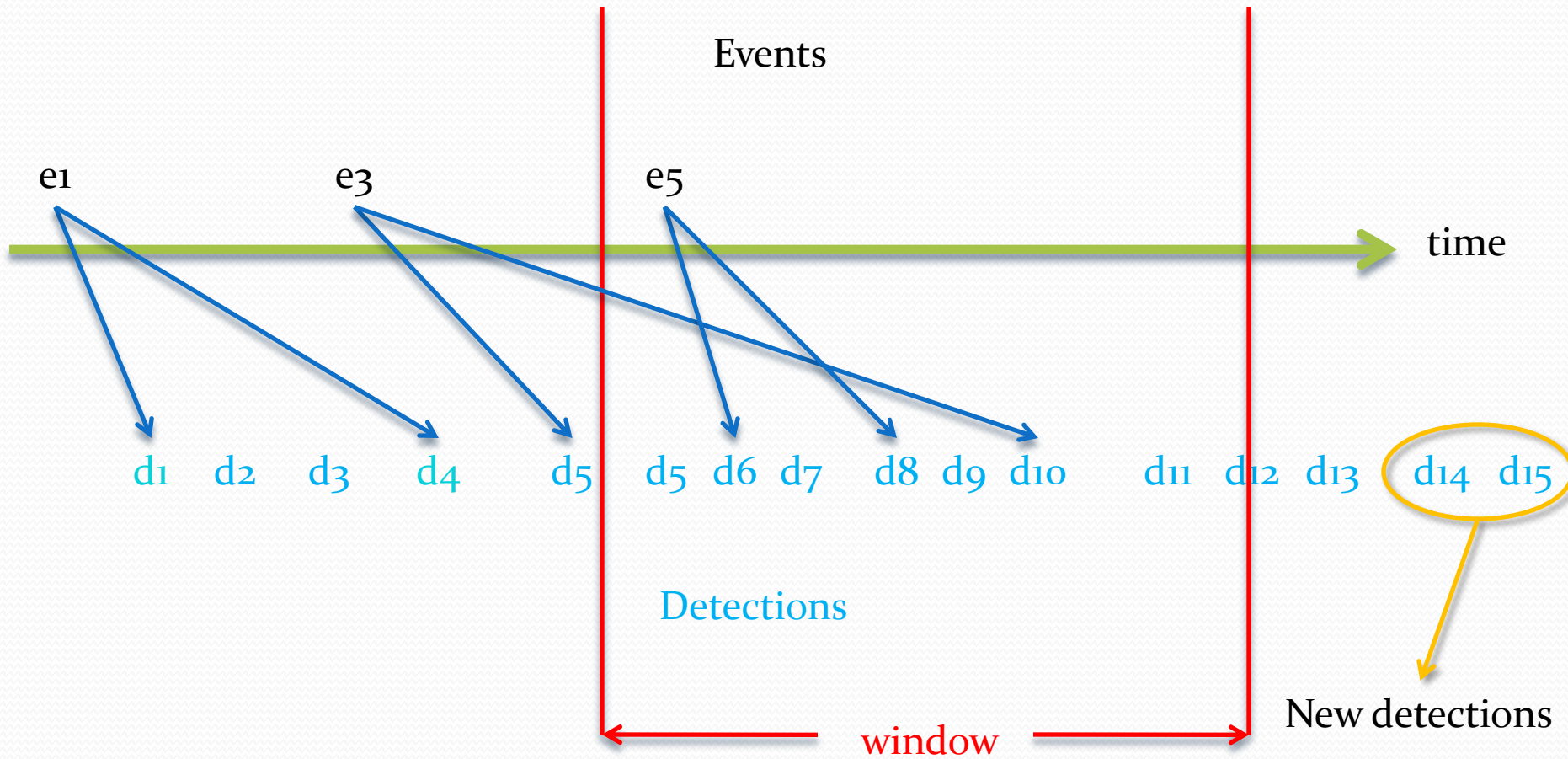
# Inference : Death Move



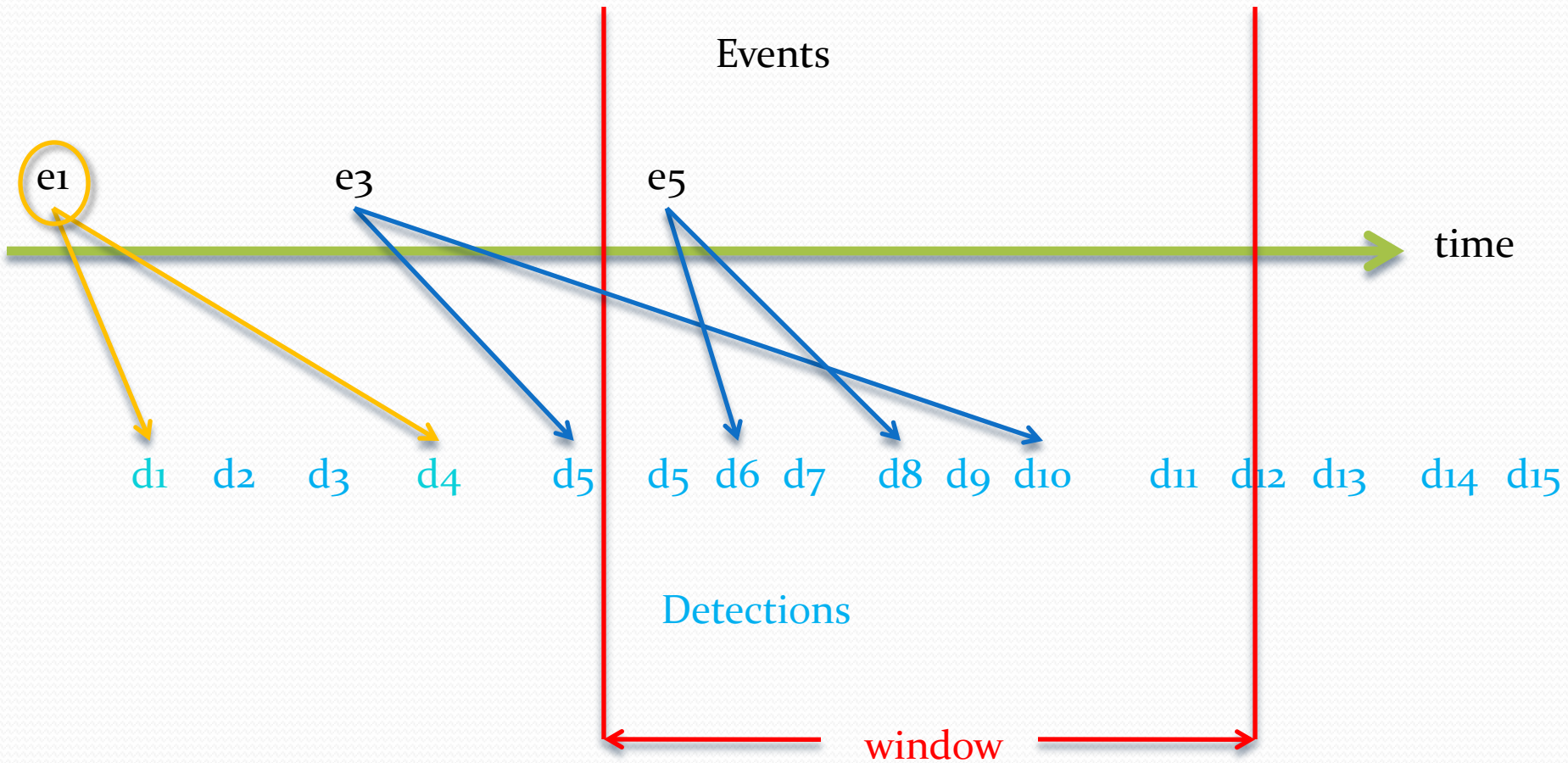
# Inference : Death Move



# Inference : Move Window Forward



# Inference : Output stable events

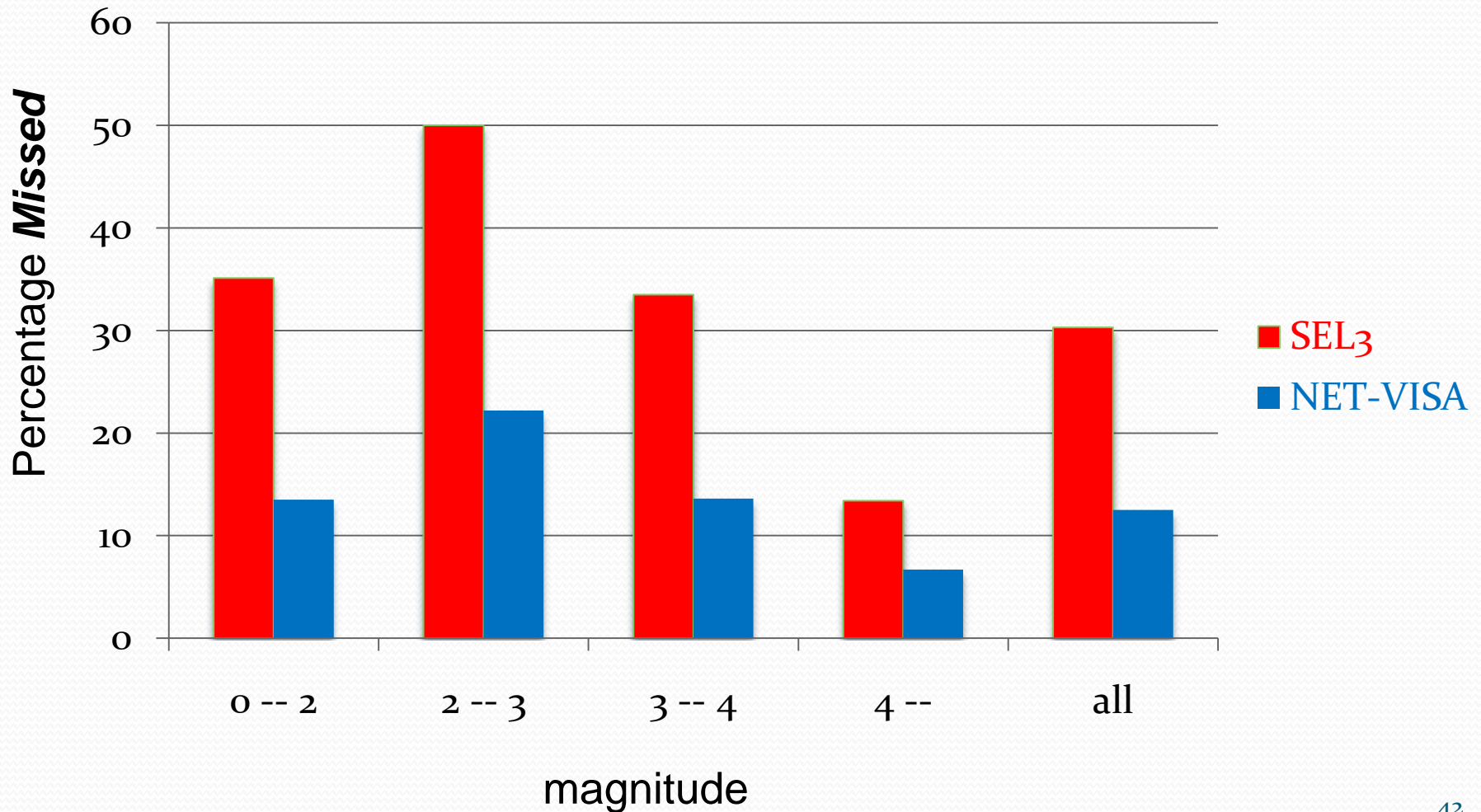




# Overview

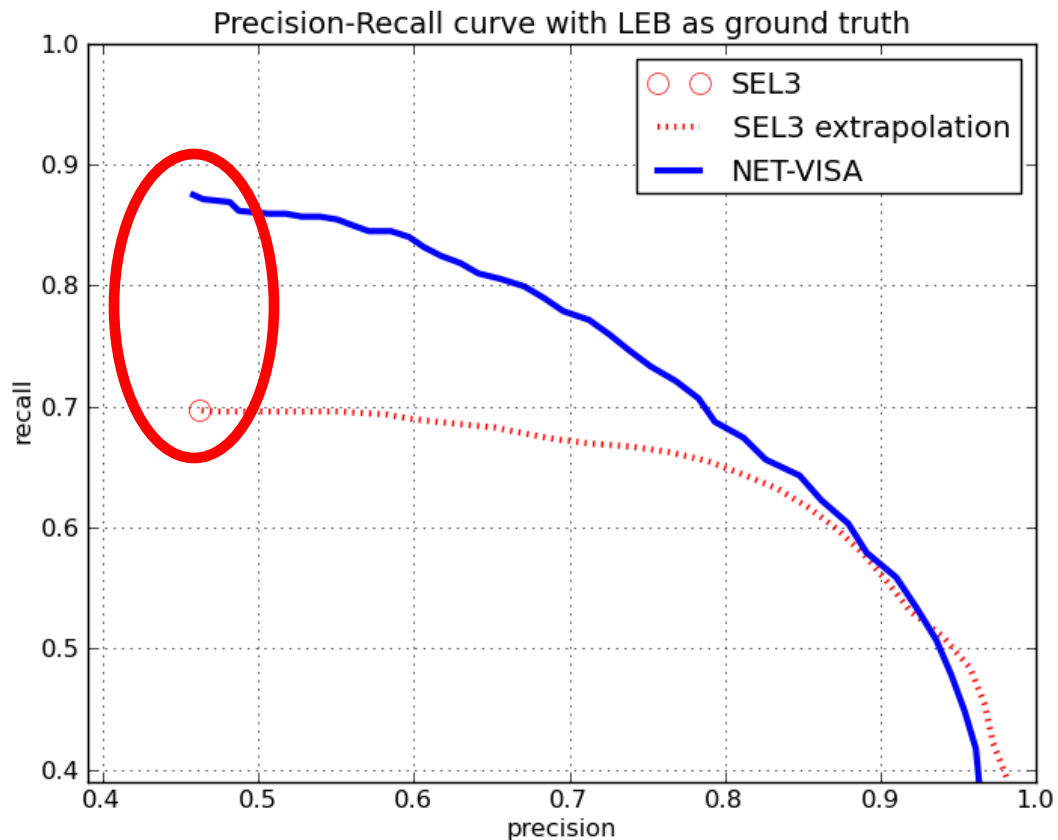
- Seismology
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# Percentage of Missed Events by Event Magnitude



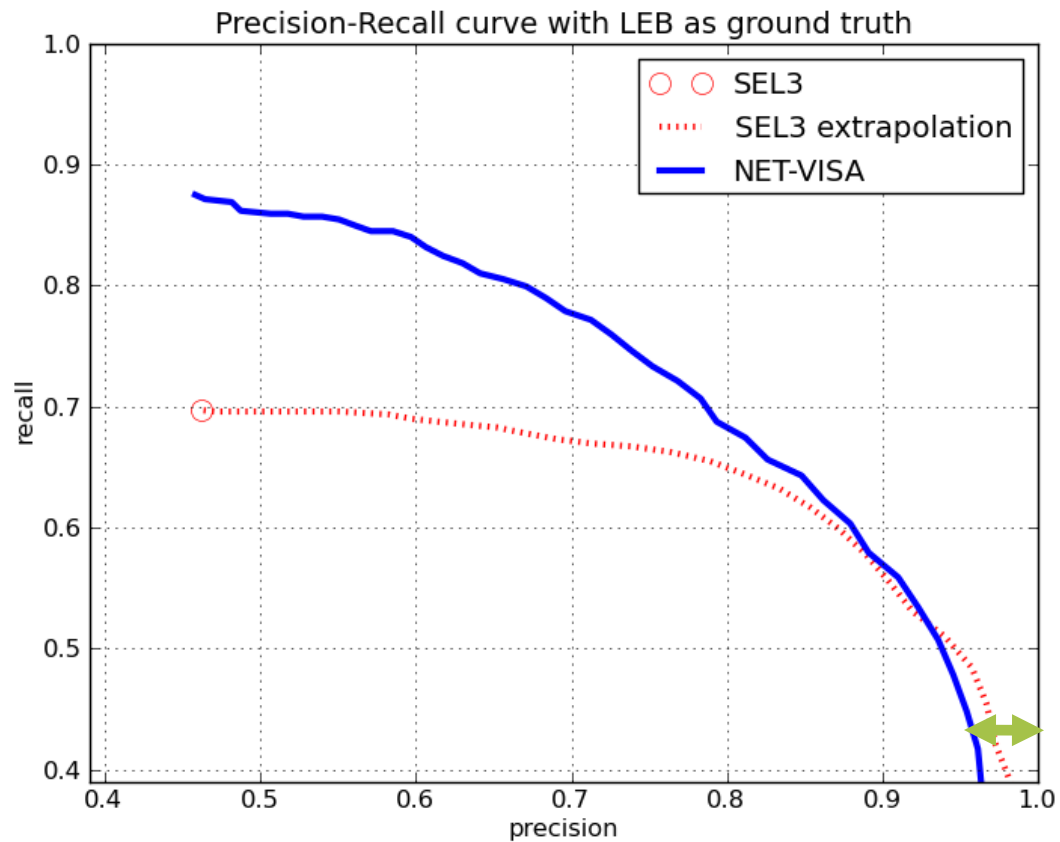
# Precision & Recall

Recall =  
fraction of  
true events  
that are  
reported



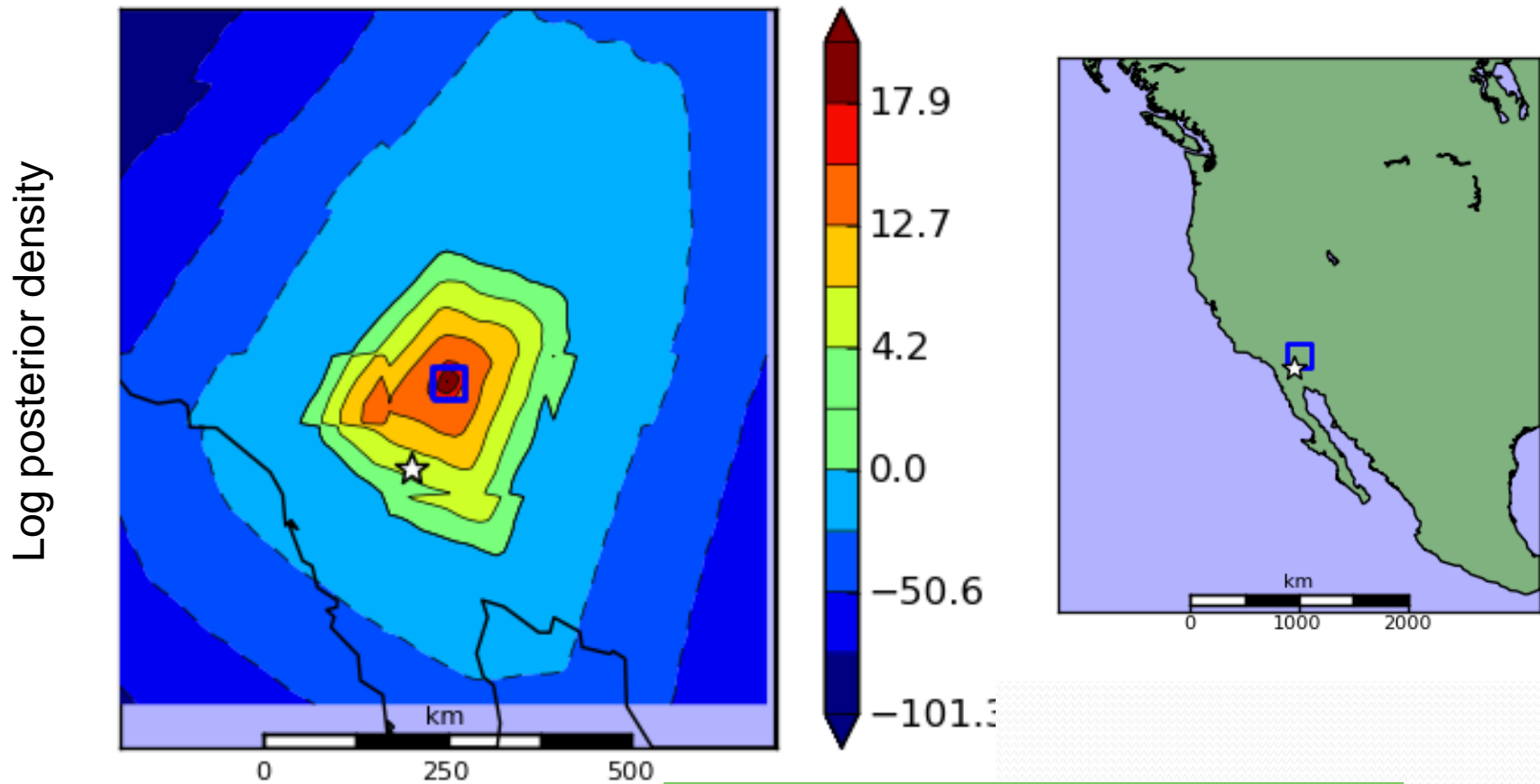
Precision = fraction of reported events that are true

# Precision & Recall



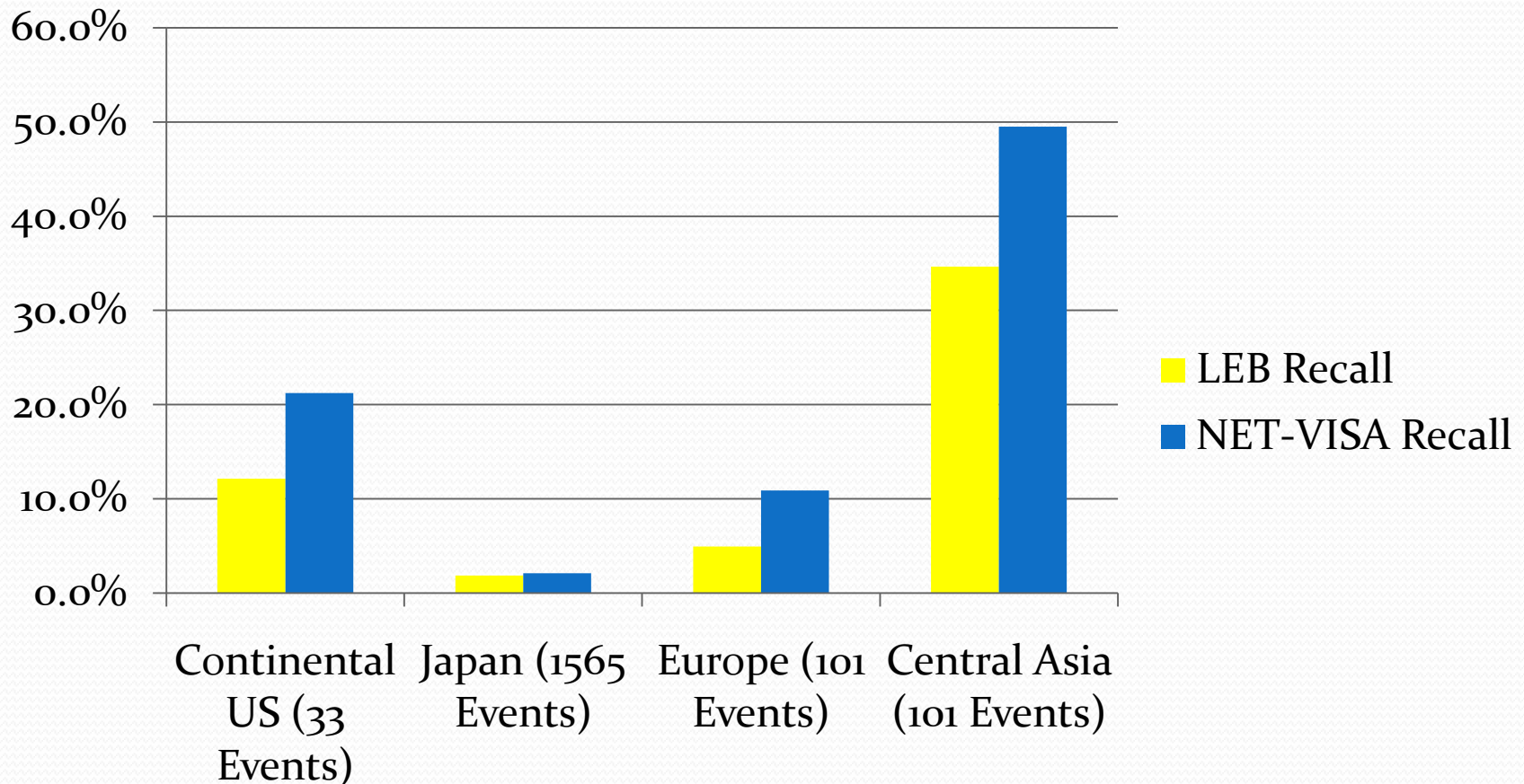
Real events missed by human analysts

# NEIC Event missed by LEB

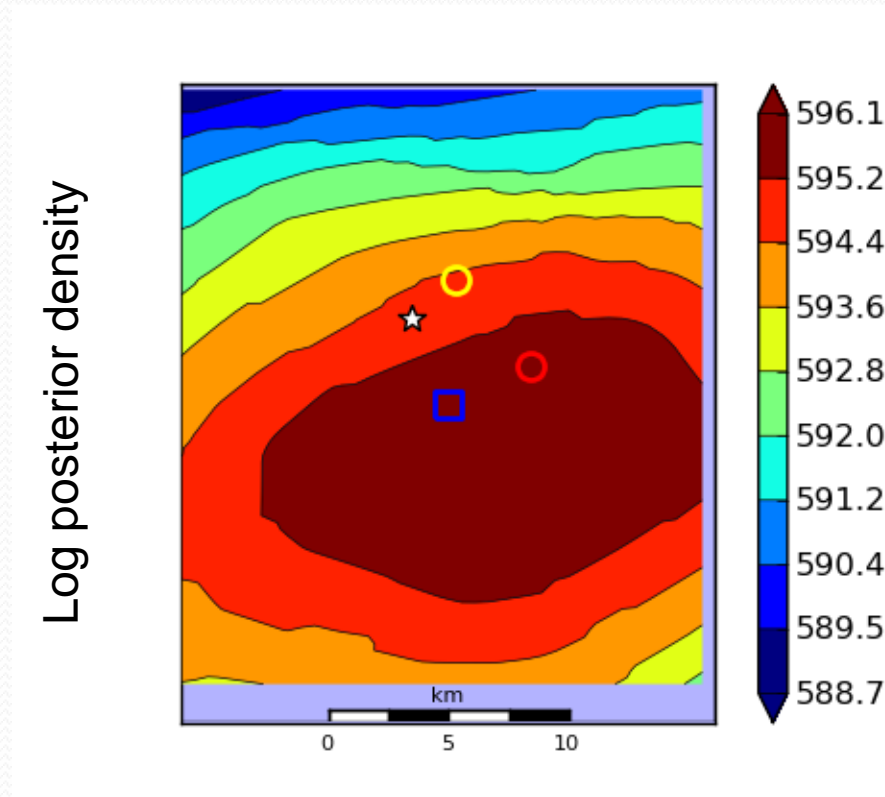


NEIC – white, and NET-VISA – blue.

# Recall on Regional Networks



# North Korean Explosion - 5/25/09



SEL3 – 39 stations  
NET-VISA – 53 stations

NEIC – white, LEB – yellow, SEL3 – red, and NET-VISA – blue.

# Conclusion

- Vertically integrated probability model of a complex, real-world process
- Combines domain knowledge with learning
- 2.5 x reduction in missed events compared to current UN system
- Currently installed for testing on CTBTO research platform
- Anticipated deployment in 2012
- Next steps:
  - Implement within general-purpose BLOG engine
  - Extend generative model to waveform level (SIG-VISA)